

UNIVERSITÉ DE VERSAILLES
SAINT-QUENTIN-EN-YVELINES



CENTRE NATIONAL D'ÉTUDES SPATIALES



RADAR-LIDAR SYNERGY FOR CLOUD STUDIES

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Workshop:
Observations and modeling of aerosol and clouds properties for climate studies
September 12-14, 2011

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MOTIVATIONS

We are interested in:

- * Cloud process studies
- * Cloud Climatologies
- * Cloud and Models:
 - * Are cloud properties well represented in GCMs?
 - * How could we improve ice cloud parameterizations?
 - * Is the cloud phase well represented in GCMs?
- * Cloud-Aerosol interaction
- * ...

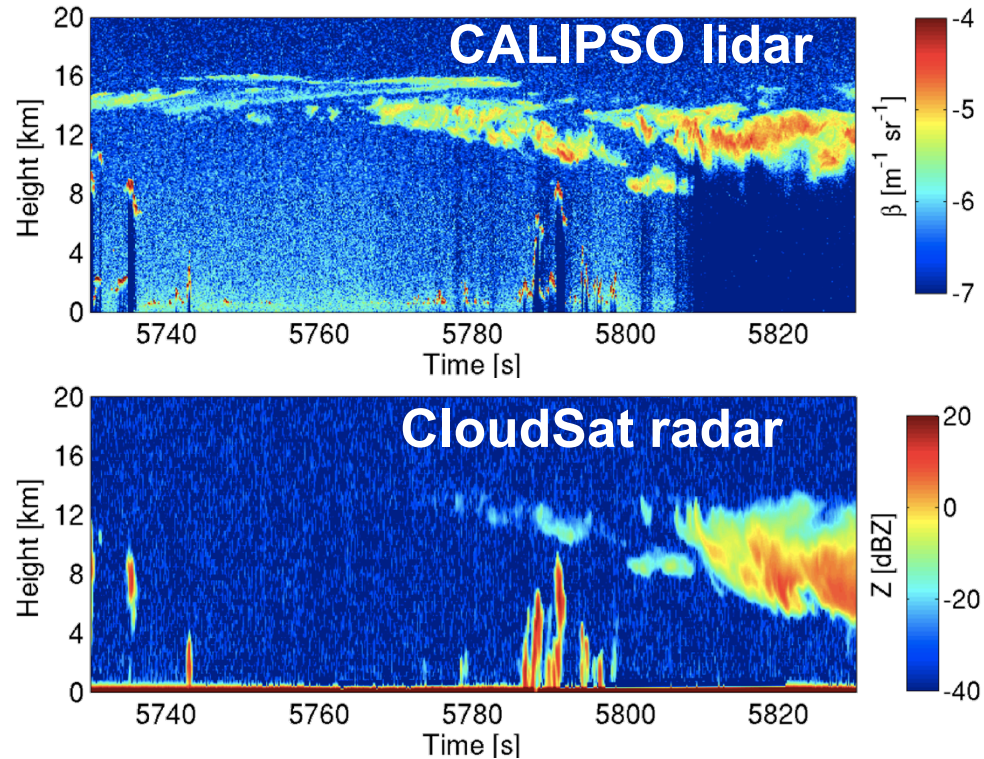
Exploit the radar-lidar synergy

- × Ground based
- × Airborne
- × CloudSat/CALIPSO+(IIR or MODIS):

WHY A SYNERGISTIC APPROACH?

Radar $Z \propto D^6$, lidar $\beta \propto D^2$ so the combination provides hydrometeor size:

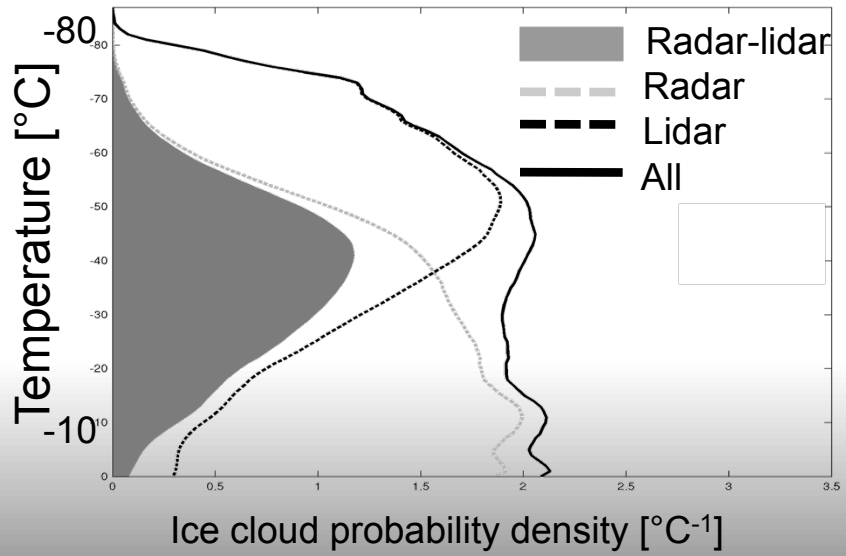
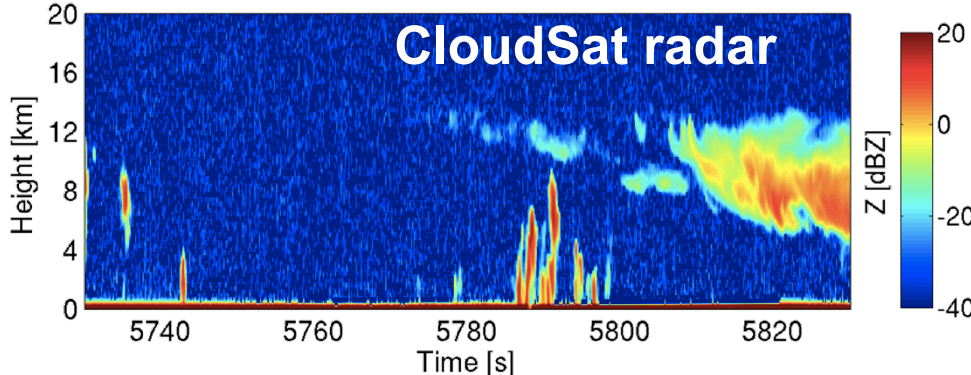
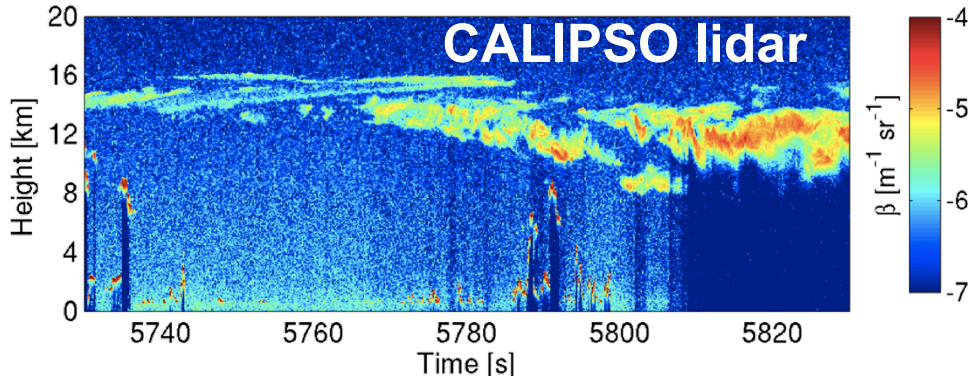
- * *Lidar*: sensitive to hydrometeor concentration, can be extinguished
- * *Radar*: very sensitive to the particle size, not very sensitivity to liquid clouds and small ice particles



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Stein et al. (2011):

- In **July 2006** and **February 2007**, cloud occurrence in the subzero troposphere was **13.3%**
- The fraction observed by radar was **65.9%**
- The fraction observed by lidar was **65.0%**
- The fraction observed by both was **31.0%**

MEASUREMENTS => CLOUD PROPERTIES

We convert instrument signals into cloud properties:

* DARDAR-MASK

- * Cloud phase: ice and liquid and supercooled layer are distinguished (Different response of radar and lidar, strong lidar signal weak radar signal)

=> Cloud fraction/cloud phase climatology

* DARDAR-CLOUD (described in Delanoë and Hogan 2010)

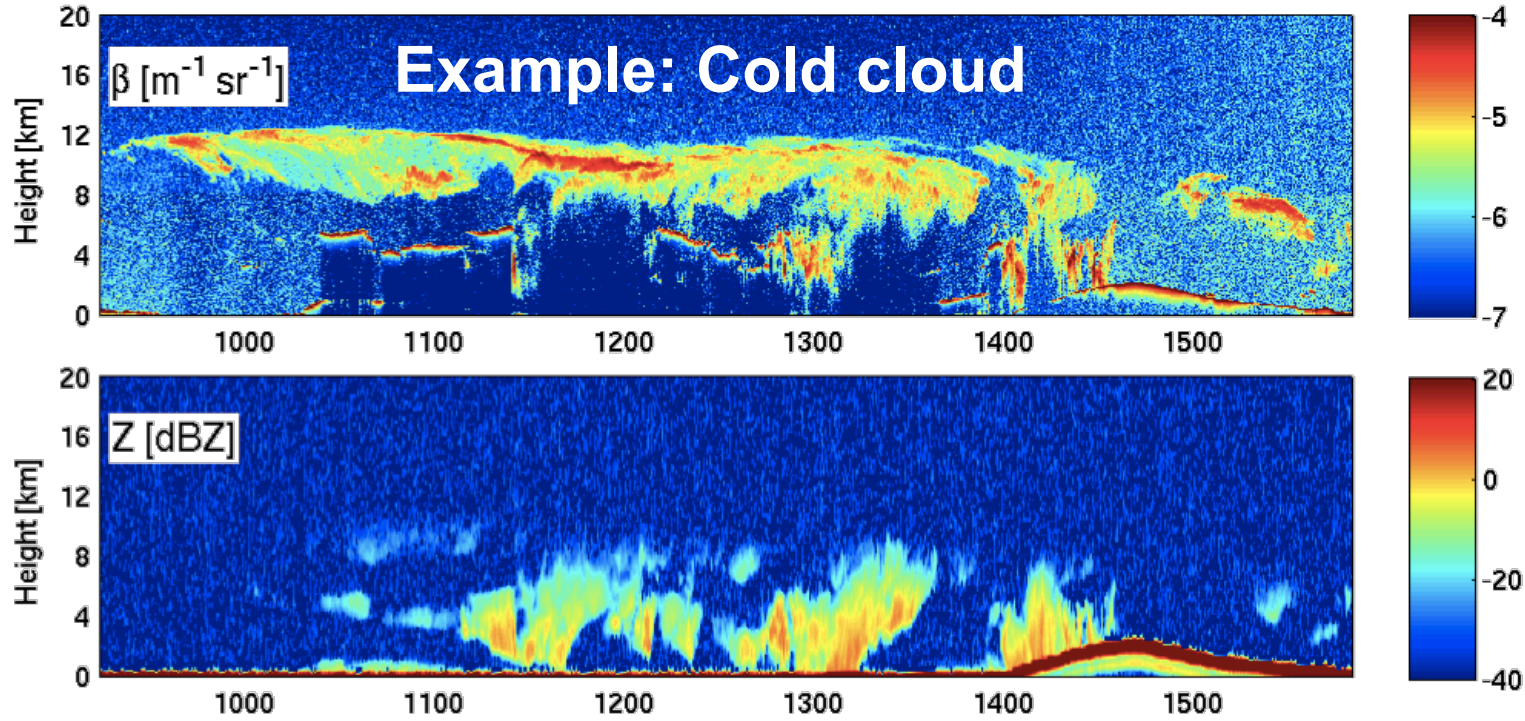
- * Retrieval of IWC, extinction, r_e etc... seamlessly between regions of cloud detected by both radar and lidar, and regions detected by just one of these two instruments.

=> Ice cloud climatology

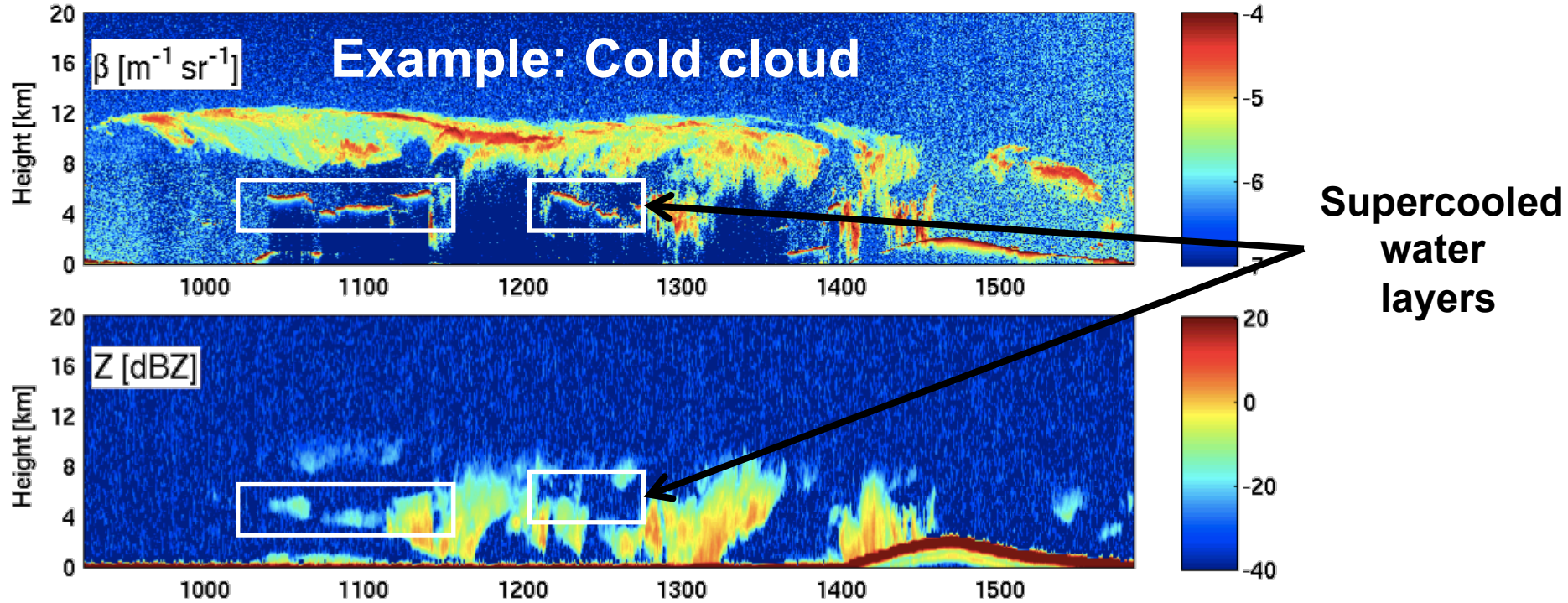
Products available at ICARE, visit www-icare.univ-lille1.fr (entire CloudSat-CALIPSO period)

Cloud phase

CLOUD PHASE IDENTIFICATION



CLOUD PHASE IDENTIFICATION



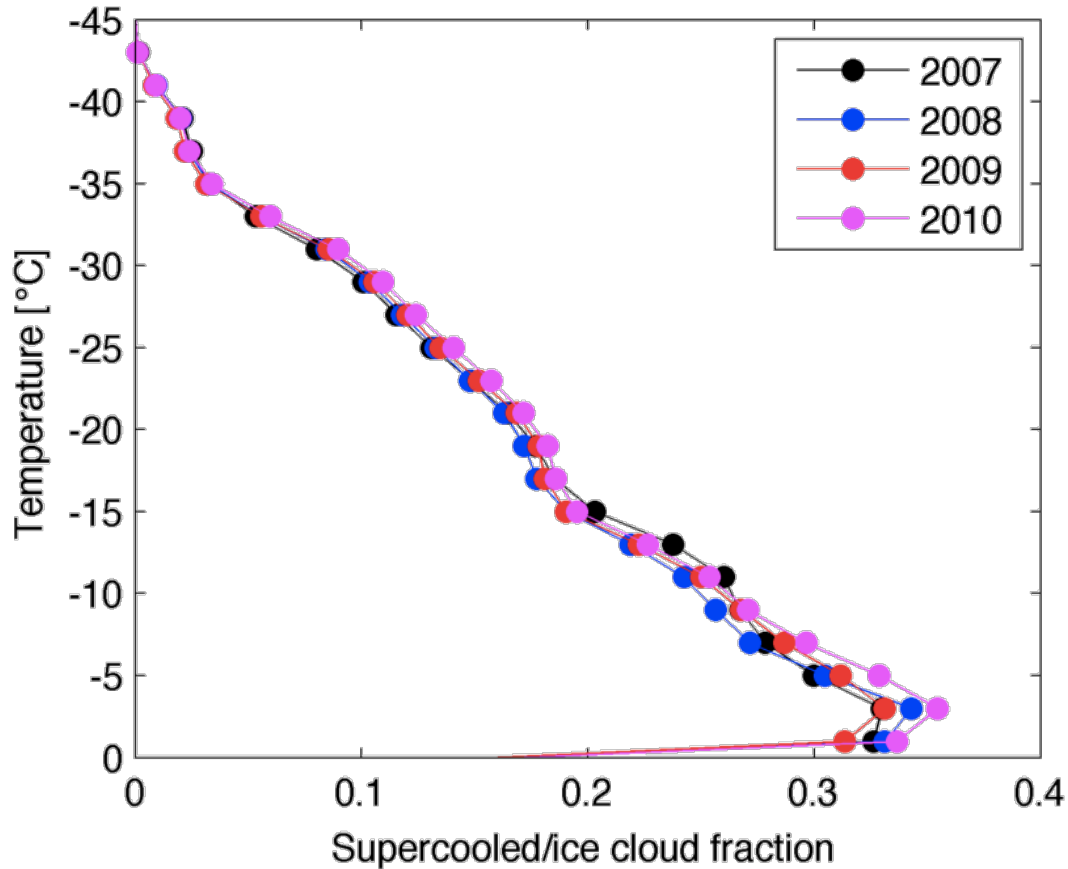
Temperature model (ECMWF) => Ice / Liquid water

Simple method :

Different response of radar and lidar in presence of supercooled liquid water:

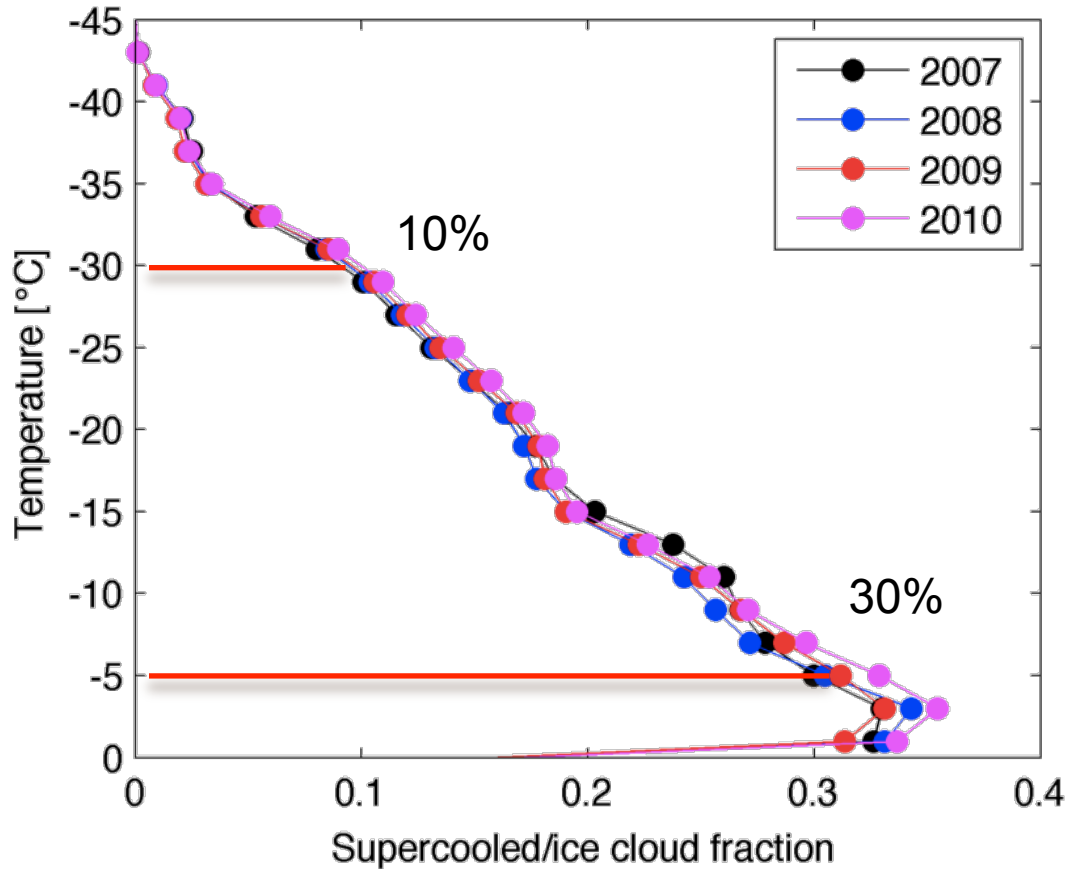
- Very strong lidar signal
 - Very weak radar signal
- Within a 300m cloud layer

SUPERCOOLED LAYER, GLOBAL DISTRIBUTION

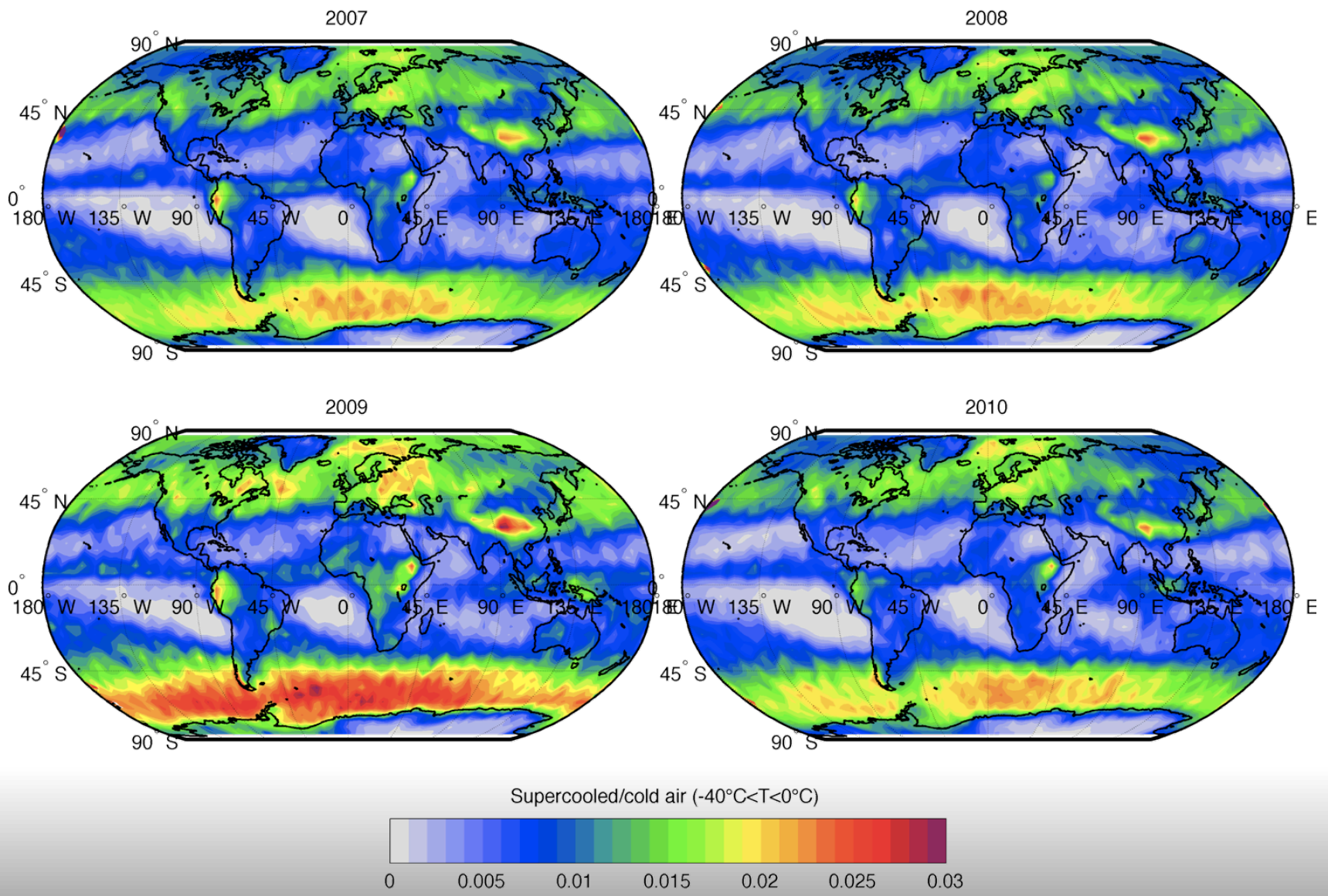


Supercooled fraction:
 ◆ $N_b(\text{sc}) / N_b(\text{cloud})$
 Fraction of sc when cloud

SUPERCOOLED LAYER, GLOBAL DISTRIBUTION



Supercooled fraction:
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 Fraction of sc when cloud



Ice cloud properties

DARDAR-CLOUD PRODUCT

Variational scheme:

We know the observations (instrument measurements) and we would like to know cloud properties : α , IWC, re...

New ray of data: define state vector

Use **classification** to specify variables describing ice cloud at each gate: *extinction coefficient and N_0^**

Delanoë and Hogan JGR,
2008-2010

Radar model

Forward model

Lidar model

Including multiple scattering
(Hogan 2006)

Radiance model

IR channels

Compare to observations:

with an **a-priori** and **measurement errors** as a constraint

Check for convergence

Not converged

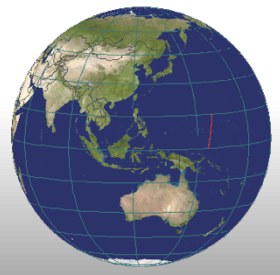
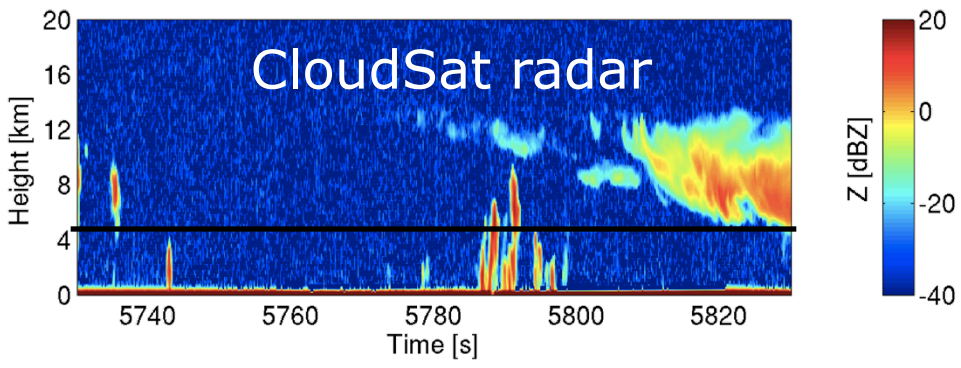
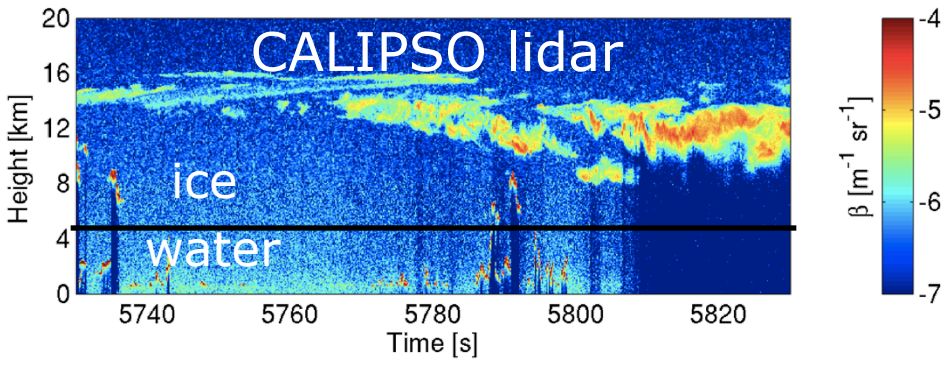
Gauss-Newton iteration

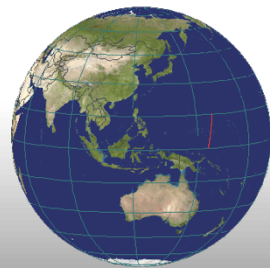
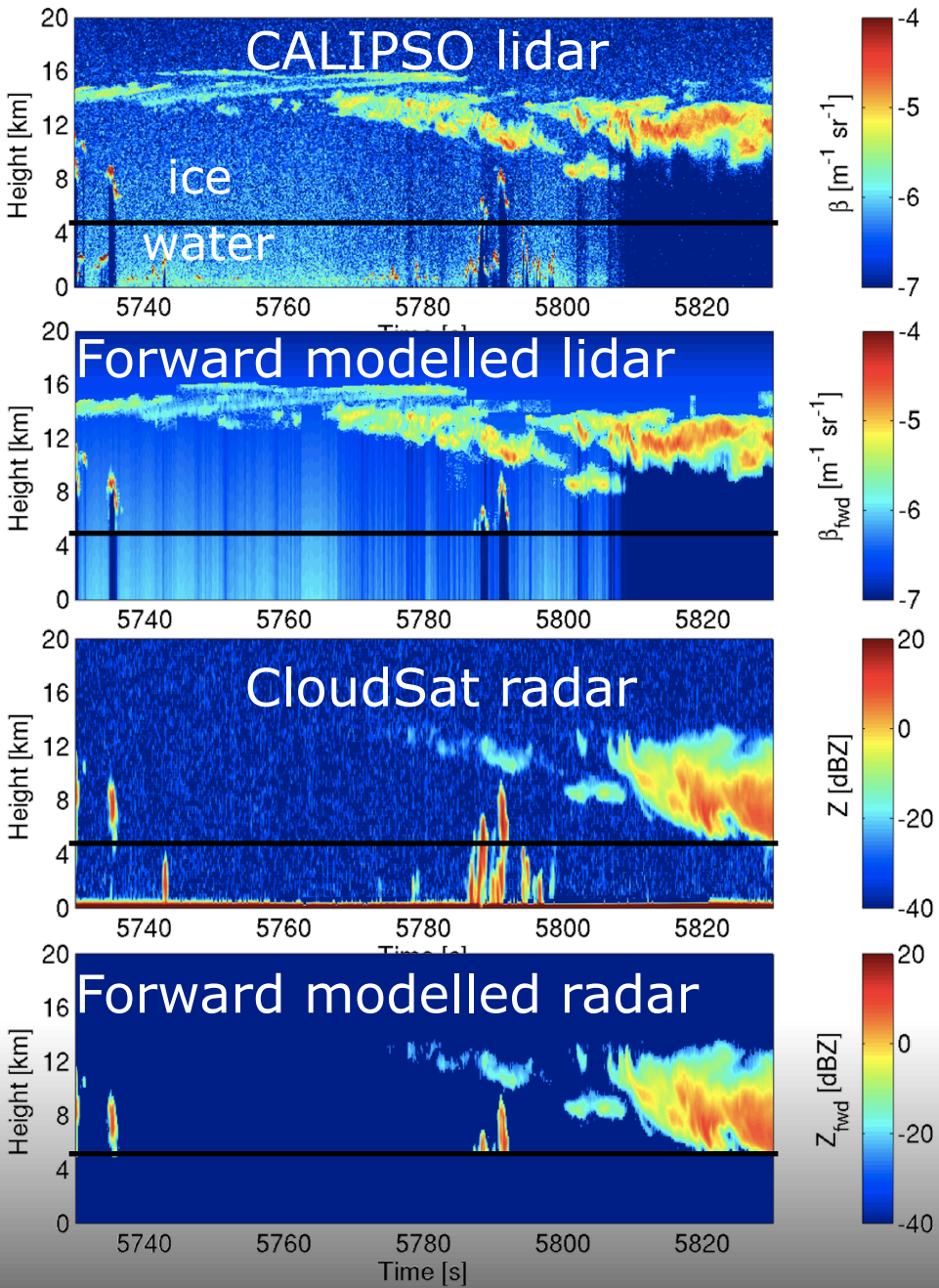
Derive a new state vector

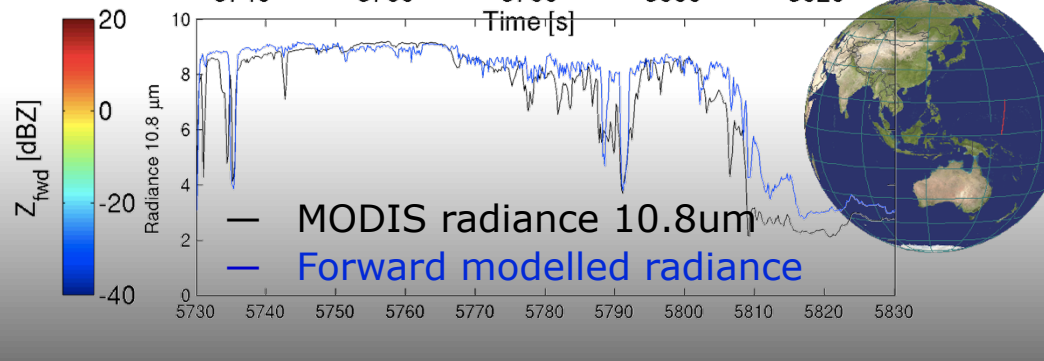
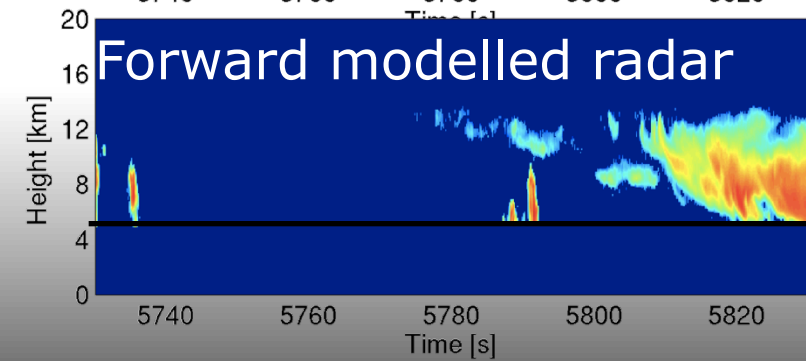
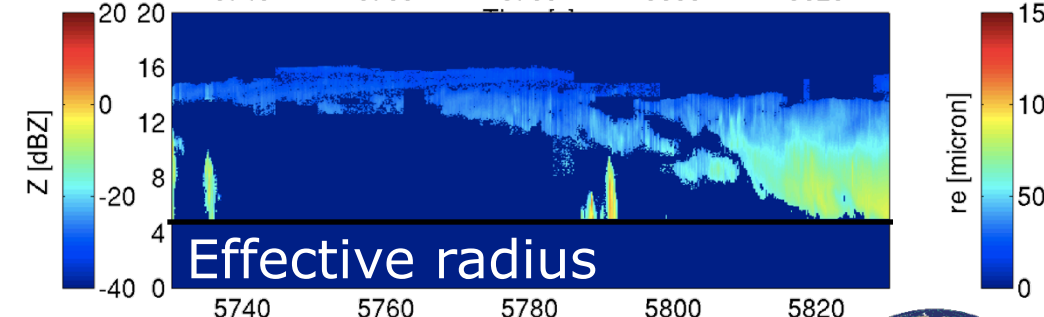
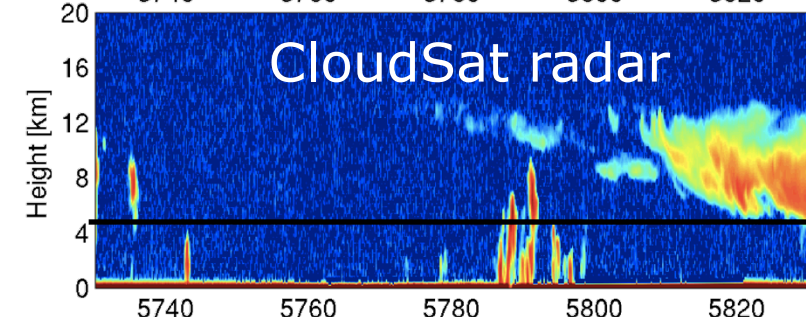
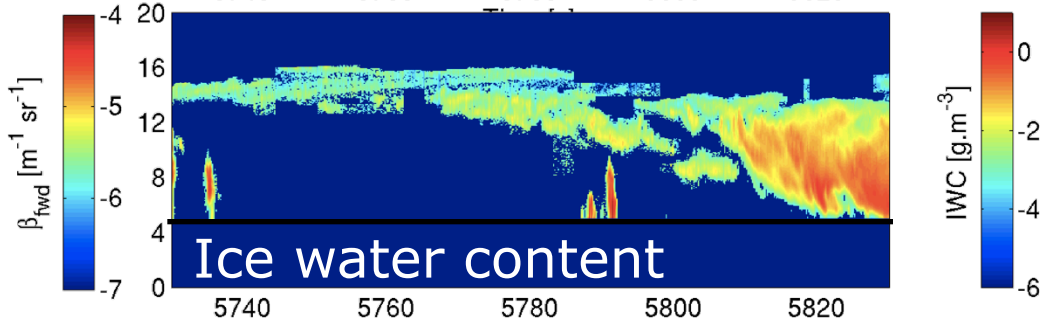
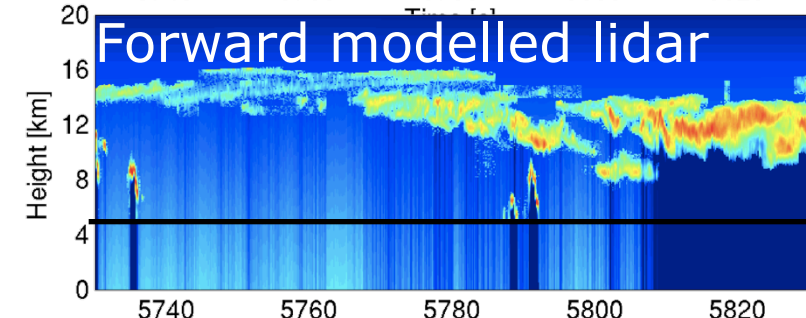
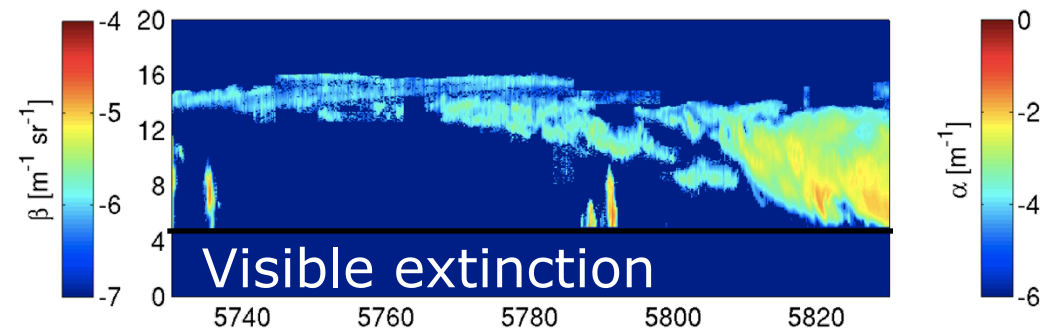
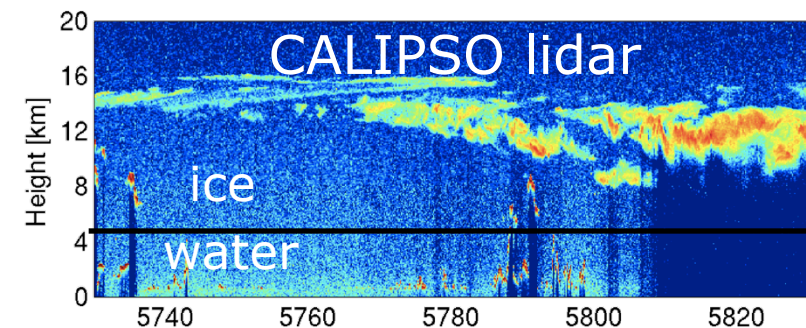
Converged

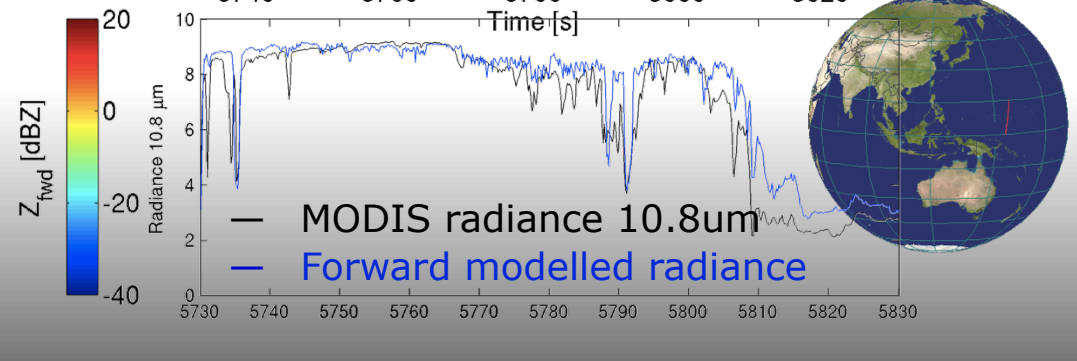
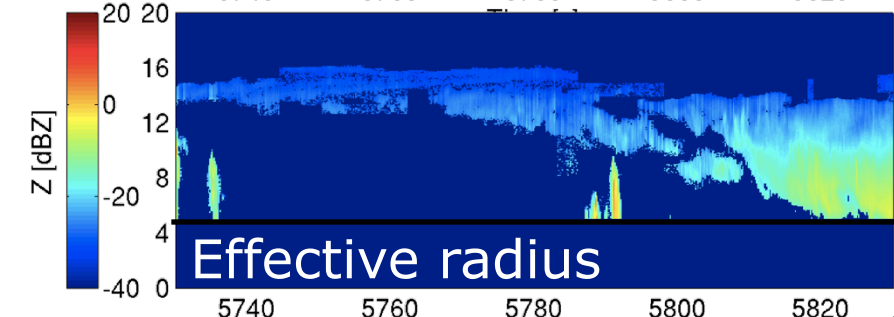
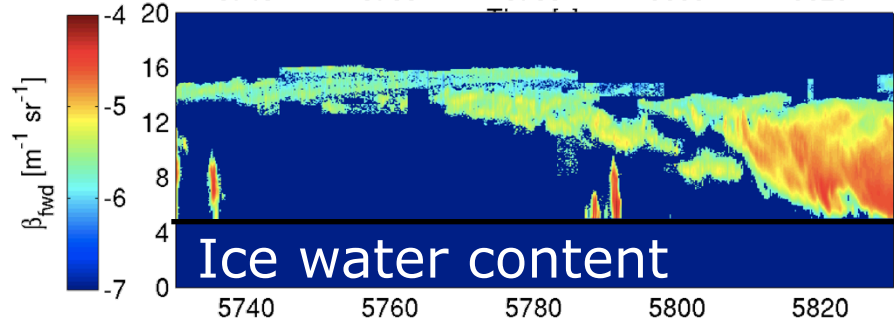
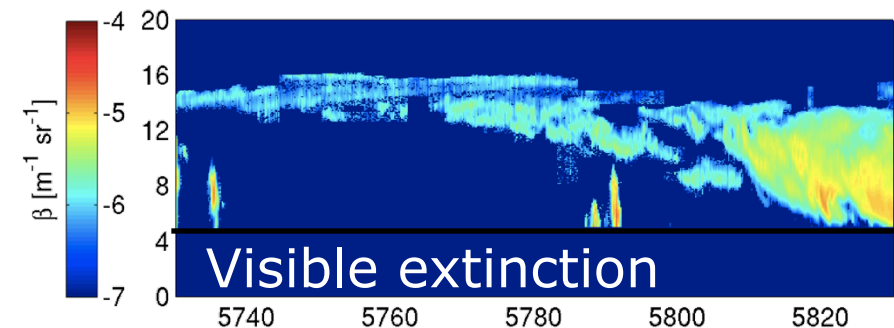
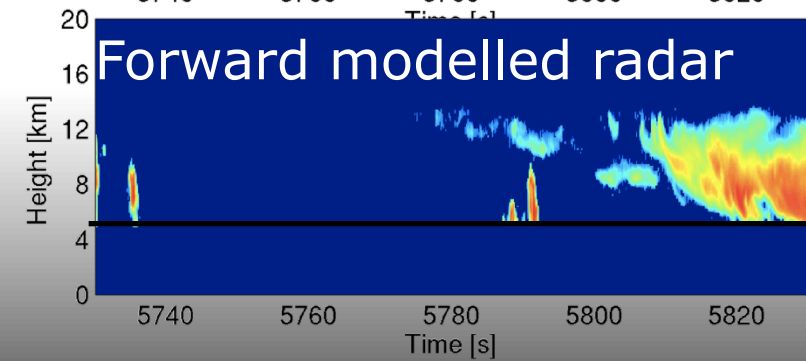
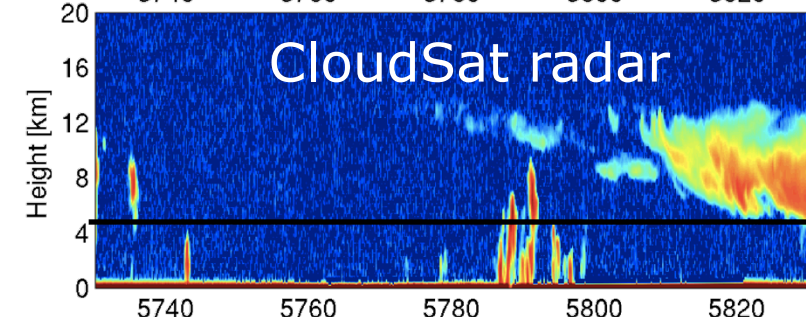
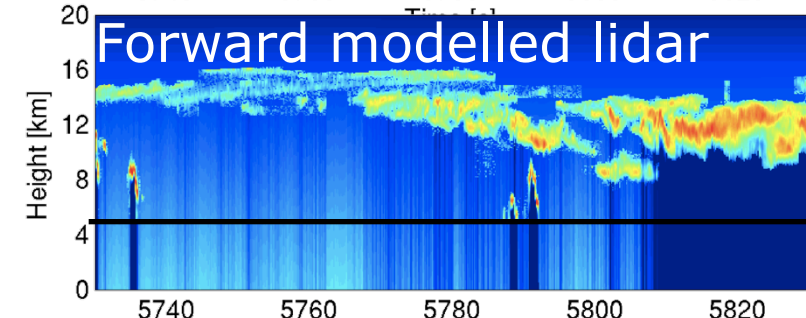
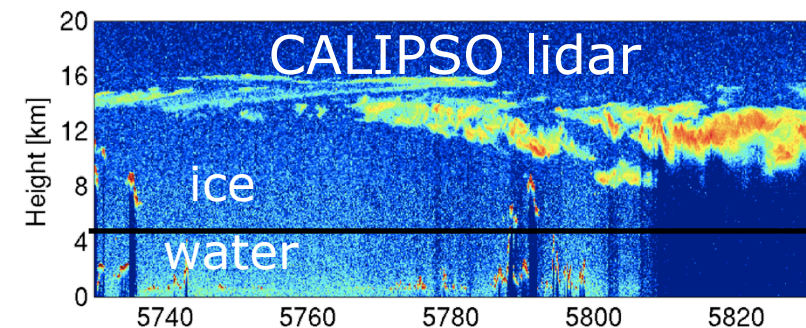
Proceed to next ray of data

Pacific Ocean 2006-9-22









MODEL EVALUATION USING RADAR-LIDAR SYNERGY

WEIGHTED OCCURRENCE IWC vs T

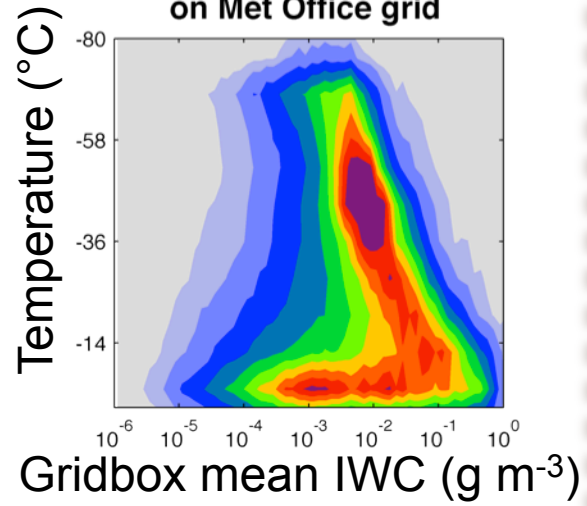
Delanoë et al 2011 (QJRMS) DOI: 10.1002/qj.882

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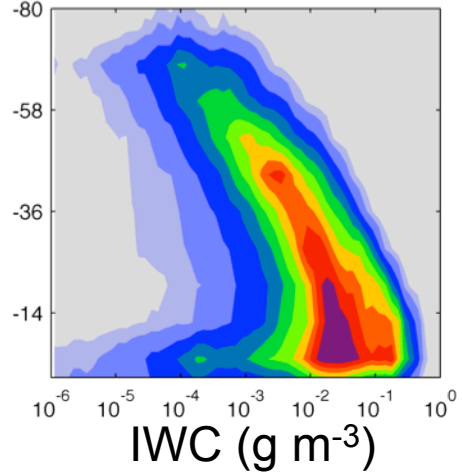
★ 3 weeks in July 2006



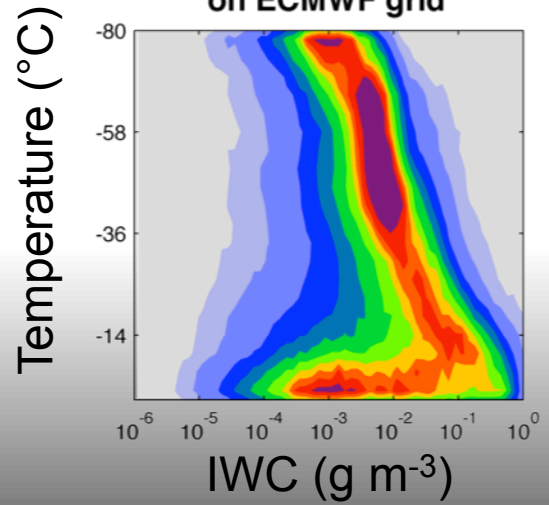
DARDAR Observations
on Met Office grid



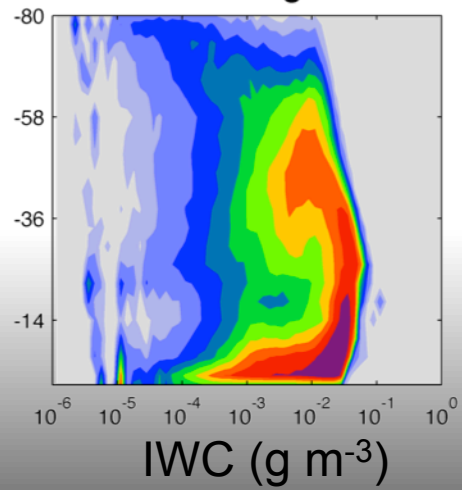
Met Office



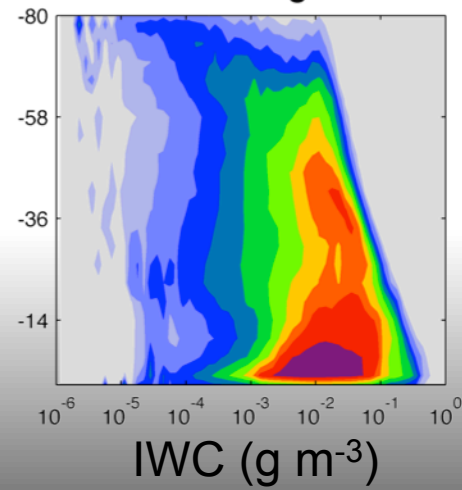
DARDAR Observations
on ECMWF grid



ECMWF
ECdiag



ECMWF
ECProg



WEIGHTED OCCURRENCE IWC vs T

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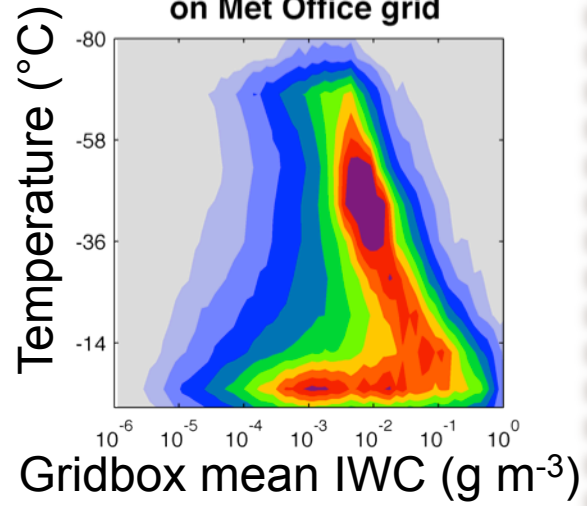
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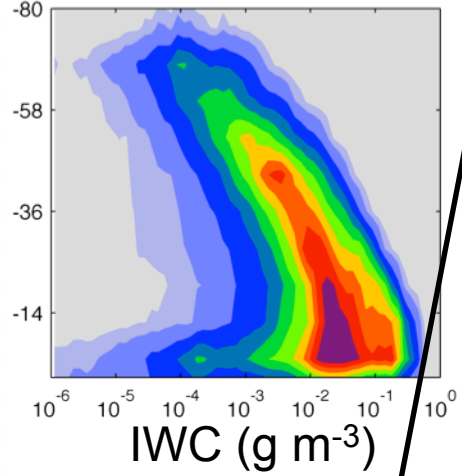
*** 3 weeks in July 2006**

- * Models capture most of the observed variability in the temperature region between -60°C and -5°C
- * "ECDiag" cut off between -20°C and 0°C due to the diagnostic snow parameterization

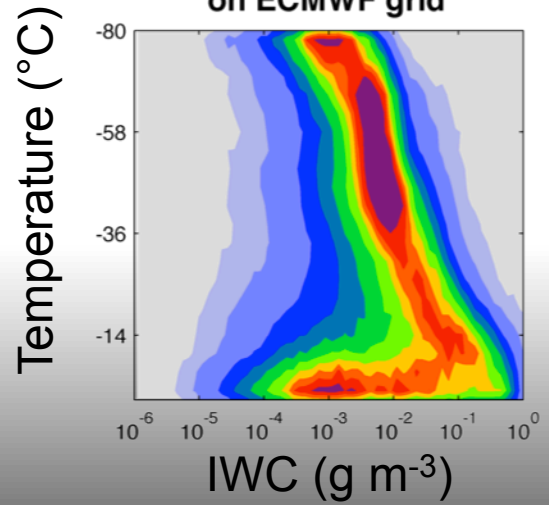
DARDAR Observations on Met Office grid



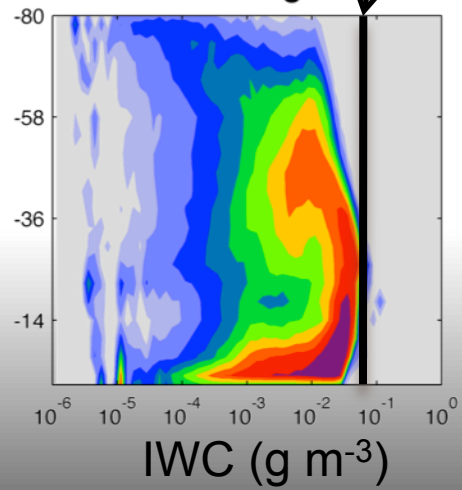
Met Office



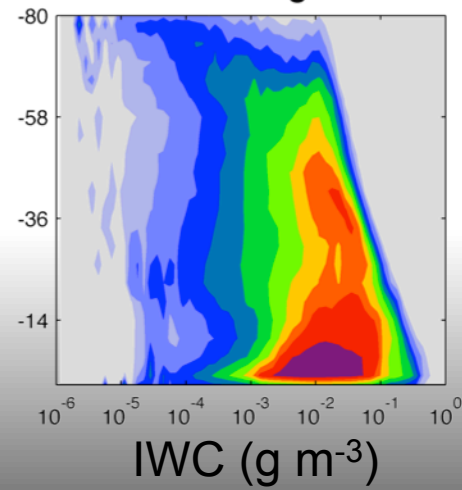
DARDAR Observations on ECMWF grid



ECMWF ECDiag



ECMWF ECProg



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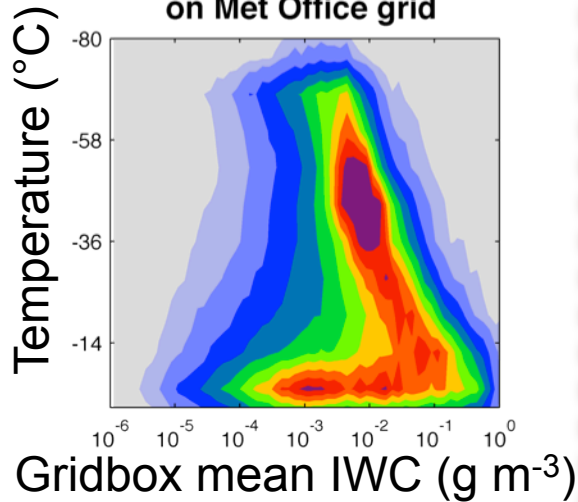
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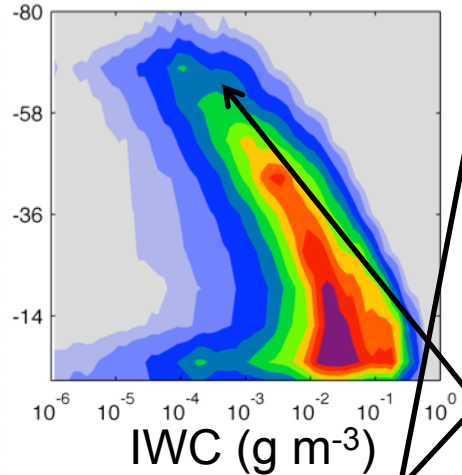
*** 3 weeks in July 2006**

- * Models capture most of the observed variability in the temperature region between -60°C and -5°C
- * "ECDiag" cut off between -20°C and 0°C due to the diagnostic snow parameterization
- * Models underestimate occurrence of the lower IWC at temperatures below -70°C .

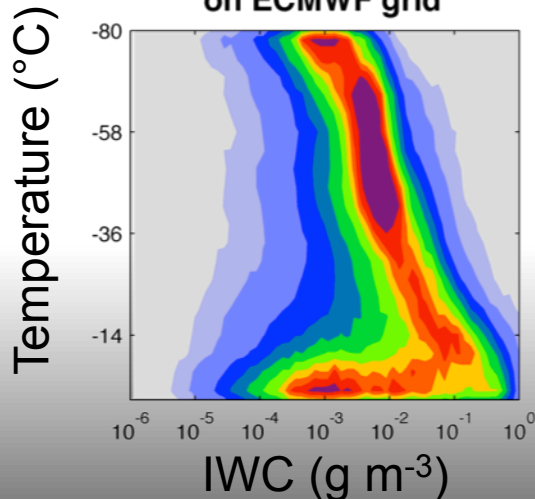
DARDAR Observations on Met Office grid



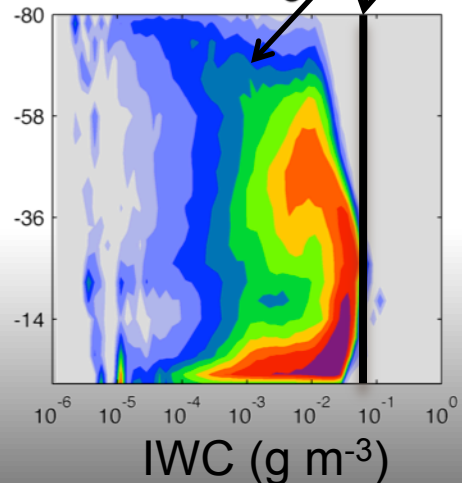
Met Office



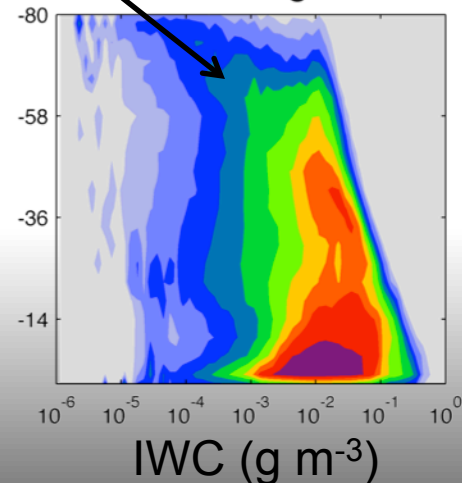
DARDAR Observations on ECMWF grid



ECMWF ECDiag



ECMWF ECProg



Product improvements:

- ✘ Improve the DARDAR-MASK: problem with a few liquid clouds
- ✘ Add the liquid cloud retrieval
- ✘ Comparison with other stand-alone products

Scientific exploitation:

- ✘ More IWC/re/extinction climatologies
- ✘ Model evaluation over several years
(Work of C. Bardeen, NCAR)
- ✘ Aerosol and Cloud
(Work of S. Massie, NCAR)

Prepare EarthCare !

DARDAR-CLOUD: KEY INFO

$$\mathbf{y} = \begin{pmatrix} \ln \beta'_1 \\ \vdots \\ \ln \beta'_n \\ Z_1 \\ \vdots \\ Z_m \\ I_{10\mu m} \\ \Delta I_{8.5-12.0\mu m} \end{pmatrix} \quad \mathbf{x} = \begin{pmatrix} \ln \alpha_1^{\text{ice}} \\ \vdots \\ \ln \alpha_n^{\text{ice}} \\ \ln N'_1 \\ \vdots \\ \ln N'_m \\ a_{\ln S} \\ b_{\ln S} \end{pmatrix}$$

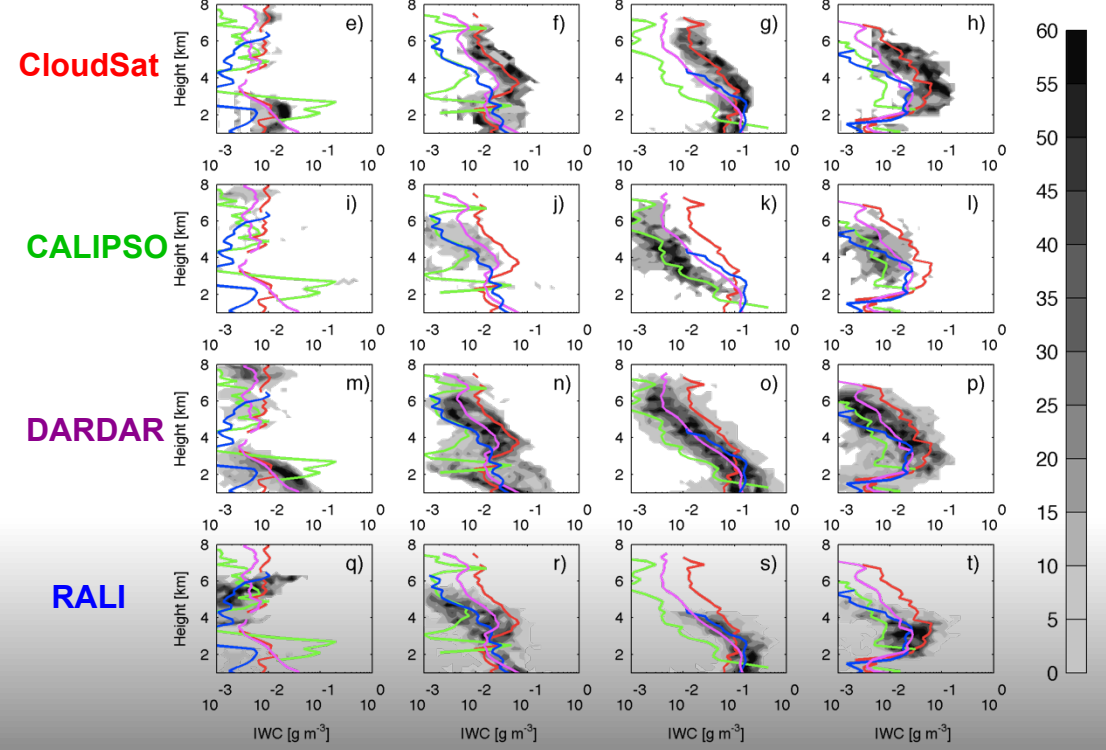
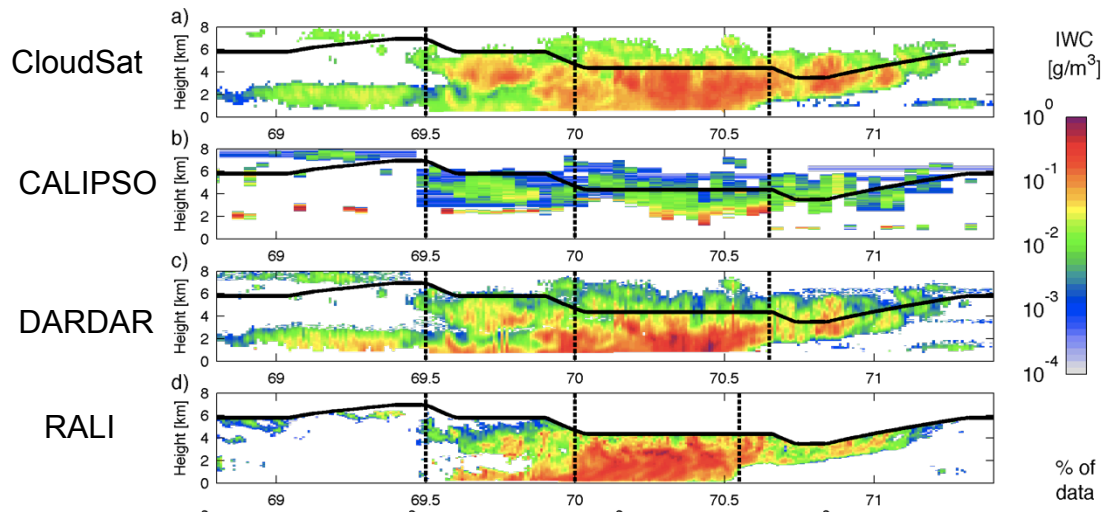
Assumptions and tricks:

- Mass-Area-size relationships from Brown and Francis 1995 and normalised PSD framework (Delanoë et al. 2005)
- A-priori $N' = N_0^* / \alpha^{0.6}$
- IWC, r_e are derived from extinction and N_0' via lookup tables

- When radar and lidar are simultaneously available: 2 moments of PSD are available.
- When only one instrument available, we rely on our a-priori $\ln N'(T)$
- S can assumed constant with height Or can be assumed linearly varying with height if radiance used $S = \exp(a_{\ln S} * T + b_{\ln S})$.
- Use molecular signal beyond the cloud as a constraint on optical depth

CASE STUDY

AIRBORNE+ATRRAIN-IN-SITU



POLARCAT campaign (1st April 2008, polar cloud)

- ✗ 2B-CWC-RO (1km-240m)
- ✗ CALIPSO Lidar Level 2 Cloud Profile data at 5 km (V3-01 version) (5km-60m)
- ✗ DARDAR (1km-60m)
- ✗ French airborne radar-lidar RALI

CloudSat: highest values of IWC
CALIPSO: lowest values of IWC
DARDAR: in between and close to RALI

VS IN-SITU

