The background of the slide is a photograph of a bright blue sky filled with soft, white, fluffy clouds. The clouds are scattered across the frame, with some larger ones on the right side and smaller ones on the left. The overall tone is bright and clear.

Retrieval of time-sequences of particle parameters from multiwavelength lidar measurements

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Information Available from Aerosol Lidar

Backscatter Lidar

Multiwavelength Lidar

- Aerosol layer heights
- Attenuated backscatter
- Extinction profile derived from backscatter
- Backscattering and extinction profiles at multiple wavelengths
- Particle size distribution at different heights
- Volume, surface, number densities, effective radius
- Complex refractive index and SSA

- Joint use of α and β - key for successful retrieval.
- The Raman lidar is based on tripled Nd:YAG laser:
Three elastic channels and two nitrogen Raman (3+2)
Backscattering β – 355, 532, 1064 nm
Extinction α – 355, 532 nm

We need to treat underdetermined problem

For every set R_{min} , R_{max} , m_R , m_I - the problem is well-determined: number of optical data = number of equations



R_{min} , R_{max} , m_R , m_I are varied and several thousands of solutions are found

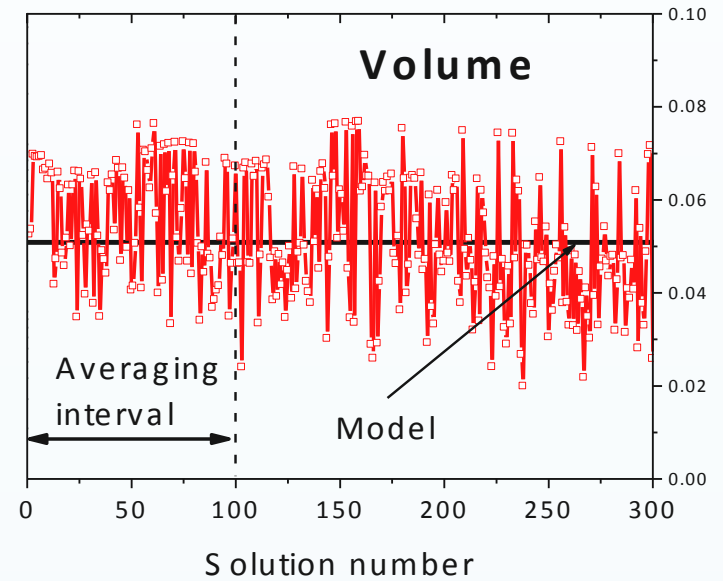
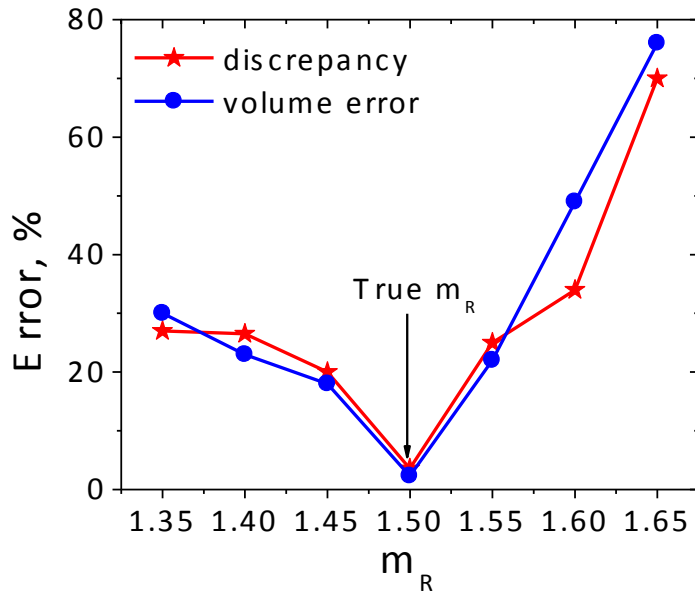


Every solution is characterized by discrepancy (difference between experimental data and data calculated from solution)



Solutions are ranged and averaged

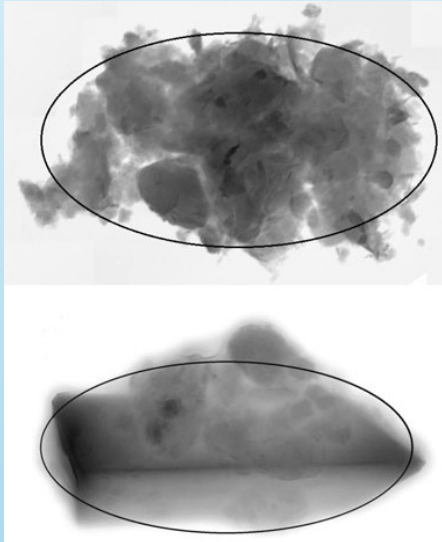
This is how it works



**Particles parameters are retrieved from synthetic optical data;
~1% of solutions are averaged.**

Treatment of Dust Particles

from M. Wiegner



Main Idea: generalizing aerosol modeling by using randomly oriented spheroids instead of spheres (Mishchenko et al. 1997)

Parameters: $dV(r)/d\ln r$, + $dn(\epsilon)/d\ln \epsilon$

r - radius of volume-equivalent sphere

ϵ - aspect ratio

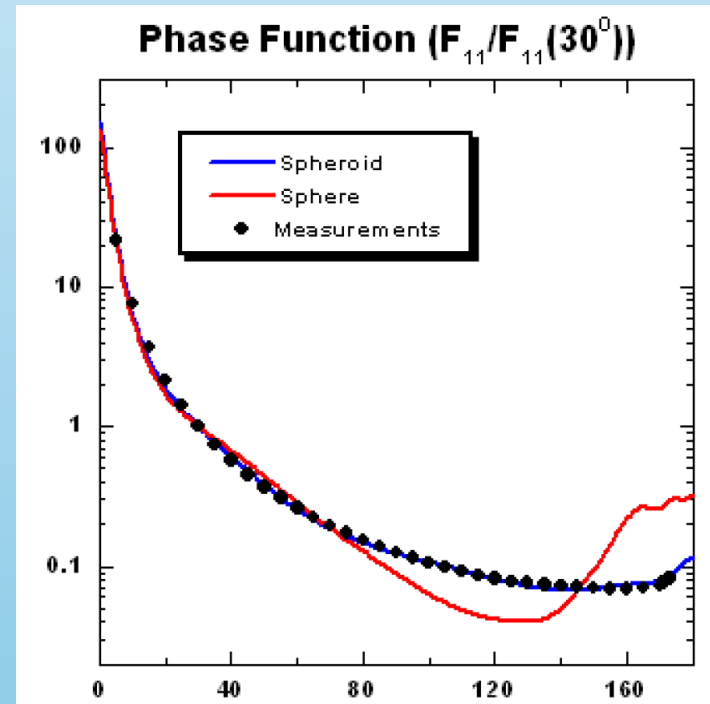
from O. Dubovik

The positive experience of AERONET is used:

- Aerosol is mixture of spheres and spheroids

$$\frac{\partial V(r)}{\partial \ln r} = \frac{\partial V^s(r)}{\partial \ln r} + \frac{\partial V^{un}(r)}{\partial \ln r} \quad \frac{\partial V^{un}(r)}{\partial \ln r} = \eta \frac{\partial V(r)}{\partial \ln r}$$

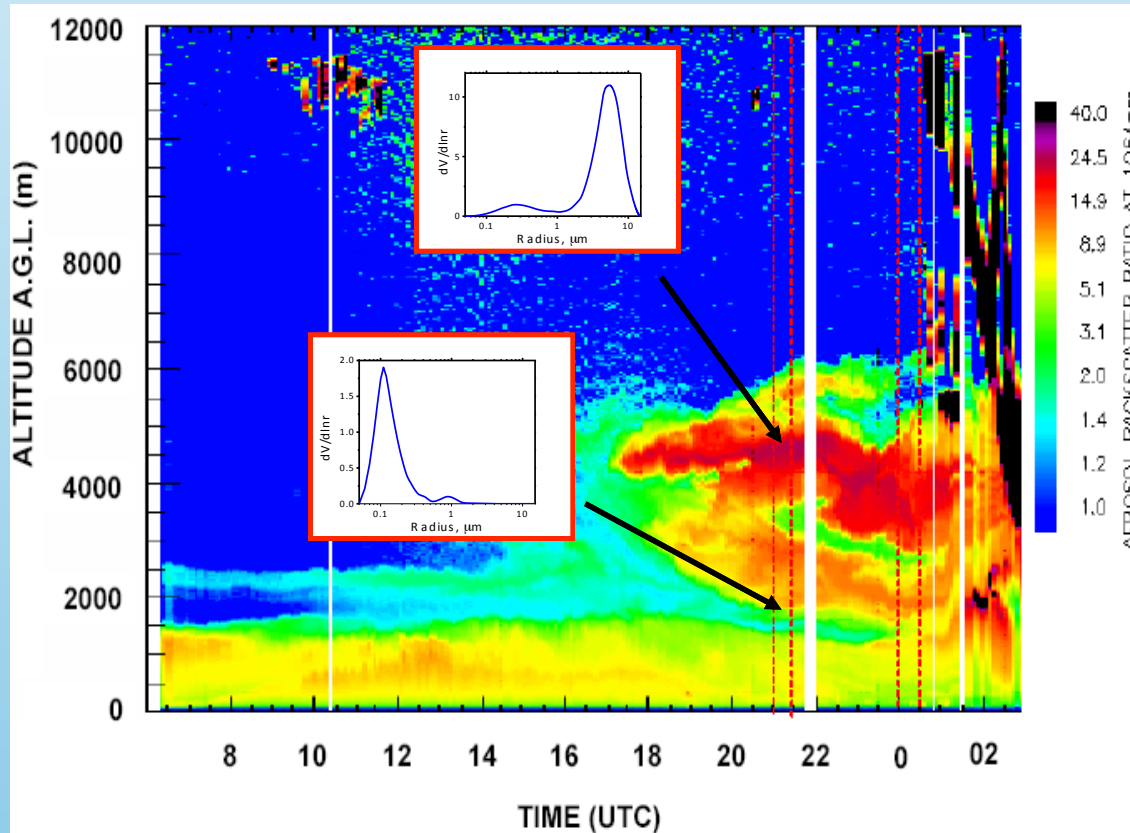
- The spheroidal kernel functions are calculated with look-up tables provided by Dubovik et al.



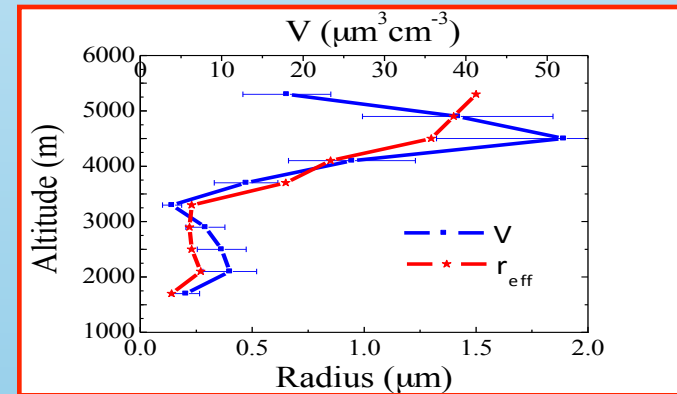
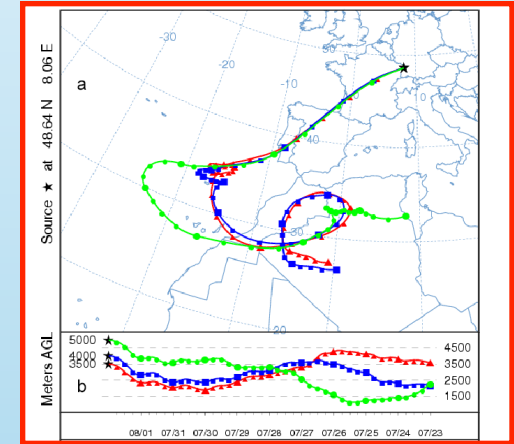
Saharan dust outbreak, Achern 2007

Data of Paolo Di Girolamo

Time evolution of the particle backscatter ratio at 1064 nm.
 Dust outbreak occurs on 1 August 2007 around 18:00. In
 the centre of plume the coarse mode dominates PSD.



Back trajectories



Profile of volume density and
 effective radius

Two Approaches to Retrieval

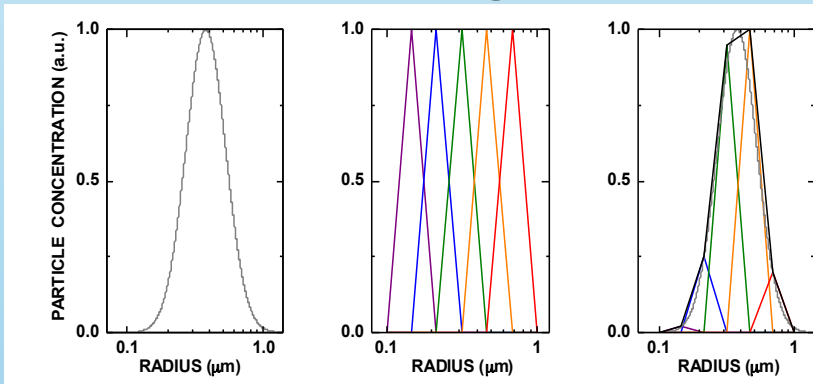
Optical data (α or β) at different λ are calculated from equation:

$$g_i = \int_0^{\infty} K_i(m, r, \lambda) \frac{dV(r)}{dr} dr$$

$$\mathbf{K}^T \mathbf{v} = \mathbf{g}$$

\mathbf{K} – discrete kernels
 \mathbf{v} – discrete volume

Inversion with regularization

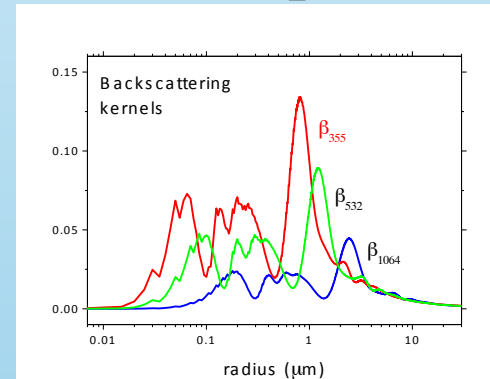


$$\mathbf{v} = \mathbf{B}\mathbf{x}$$

$$\mathbf{g} = \mathbf{K}^T \mathbf{B}\mathbf{x} = \mathbf{A}\mathbf{x}$$

$$\mathbf{x} = (\mathbf{A}^T \mathbf{A} + \gamma \mathbf{H})^{-1} \mathbf{A}^T \mathbf{g}$$

Kernels expansion



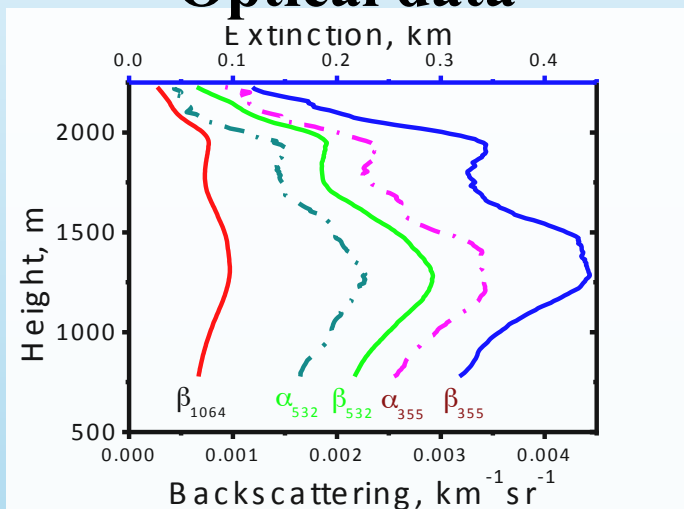
$$\mathbf{v} = \mathbf{K}\mathbf{x} + \mathbf{v}_{\perp} = \mathbf{v}_g + \mathbf{v}_{\perp}$$

$$\mathbf{g} = \mathbf{K}^T \mathbf{K} \mathbf{x} + \mathbf{K}^T \mathbf{v}_{\perp} = \mathbf{K}^T \mathbf{K} \mathbf{x}$$

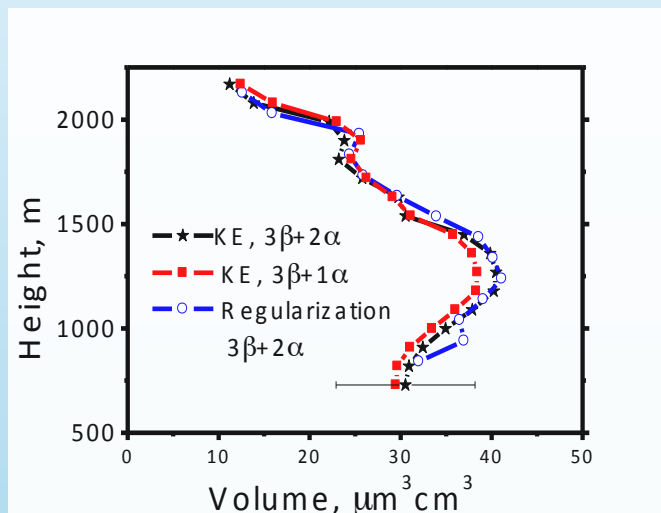
$$\mathbf{x} = (\mathbf{K}\mathbf{K}^T)^{-1} \mathbf{g}$$

Comparison of regularization and KE (Measurements were performed in GSFC)

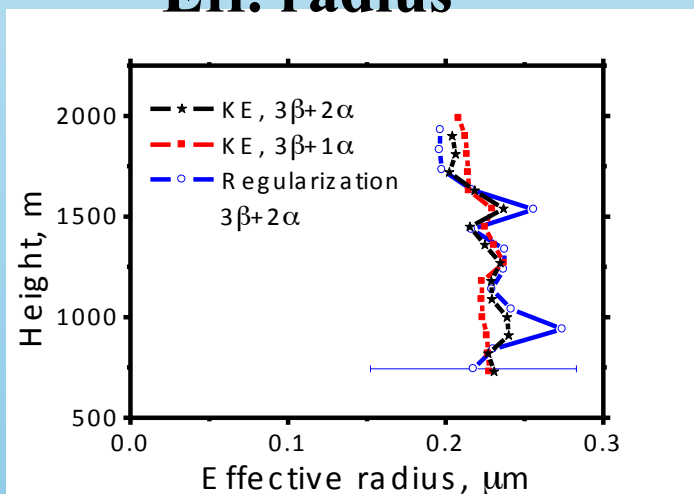
Optical data



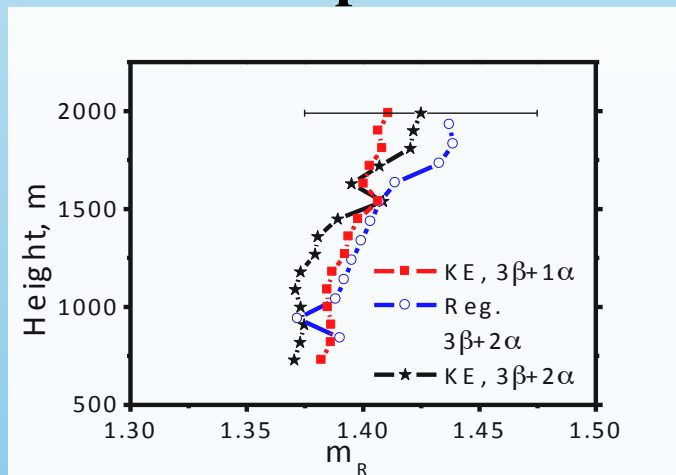
Volume



Eff. radius



Real part

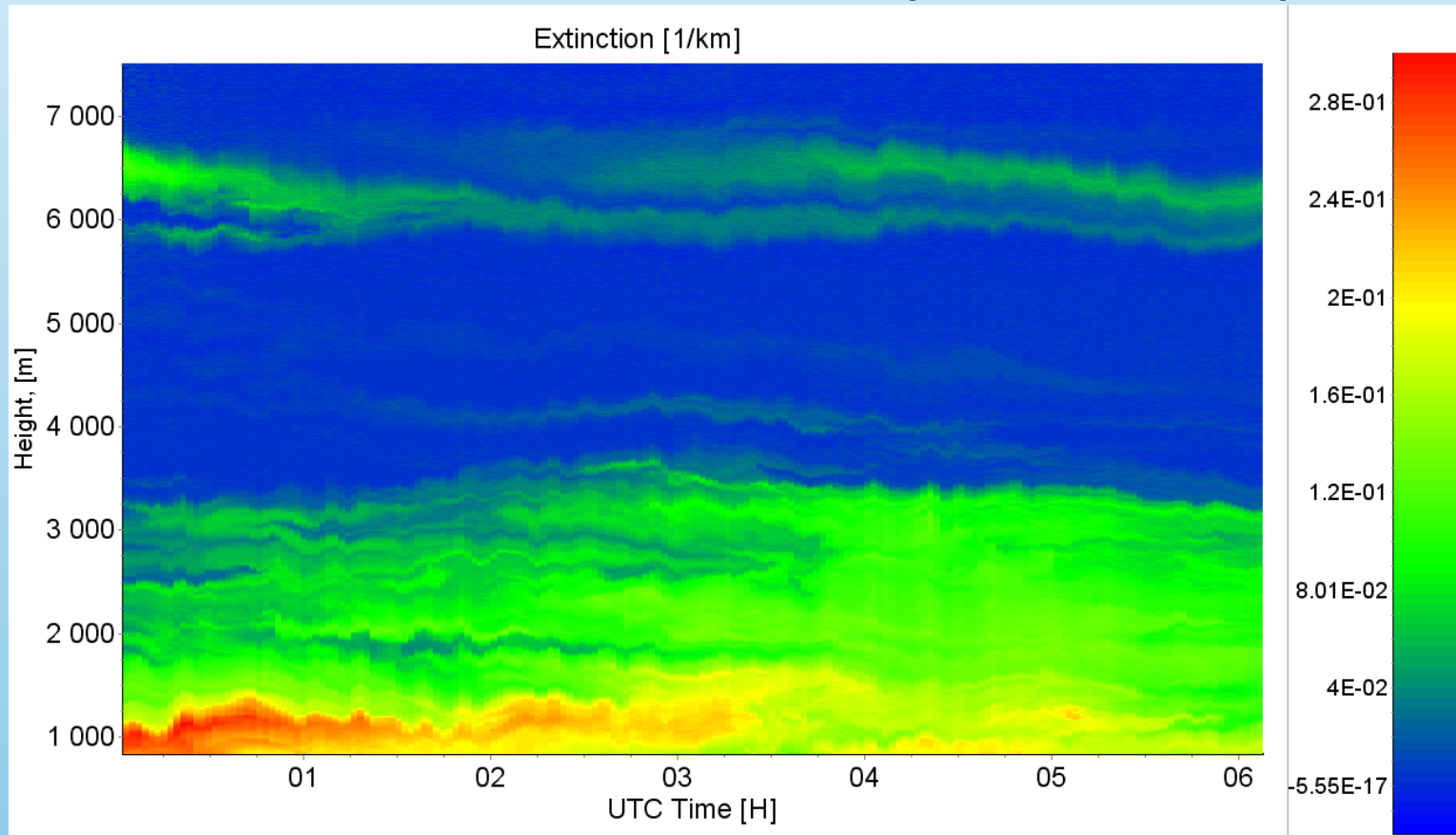


Results obtained in Summer 2011 in GSFC during DISCOVERY campaign

20 July. Extinction at 532 nm is calculated by Klett.

Height res. – 7.5 m, temporal res. – 2 min.

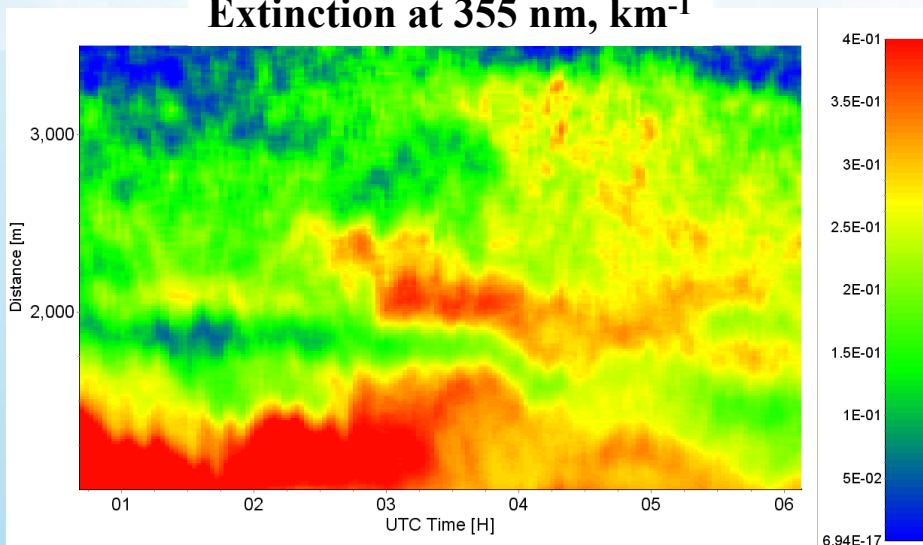
Laser: 300 mJ at 355 nm, 50 Hz, Telescope – 400 mm aperture



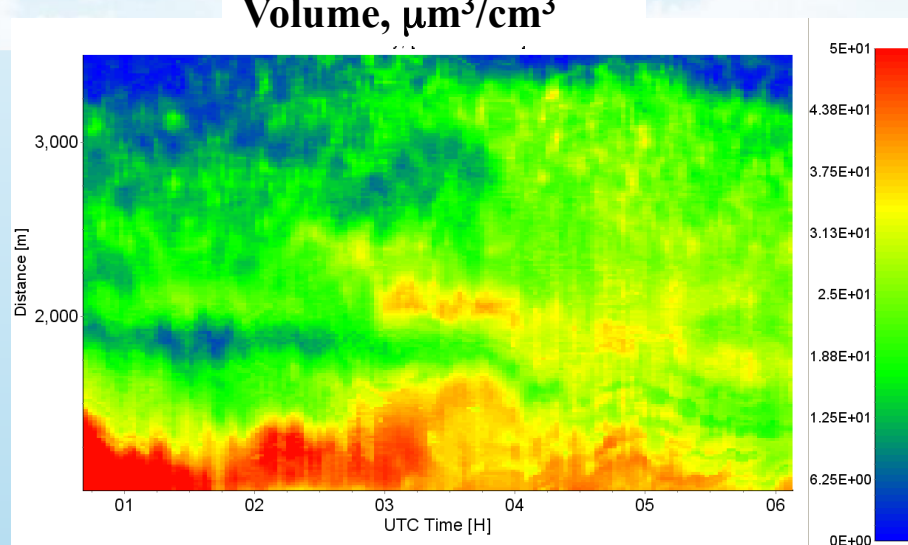
Retrieval particle parameters from $3\beta+1\alpha$ set.

Height res. ~ 100 m, temporal res. – 6 min

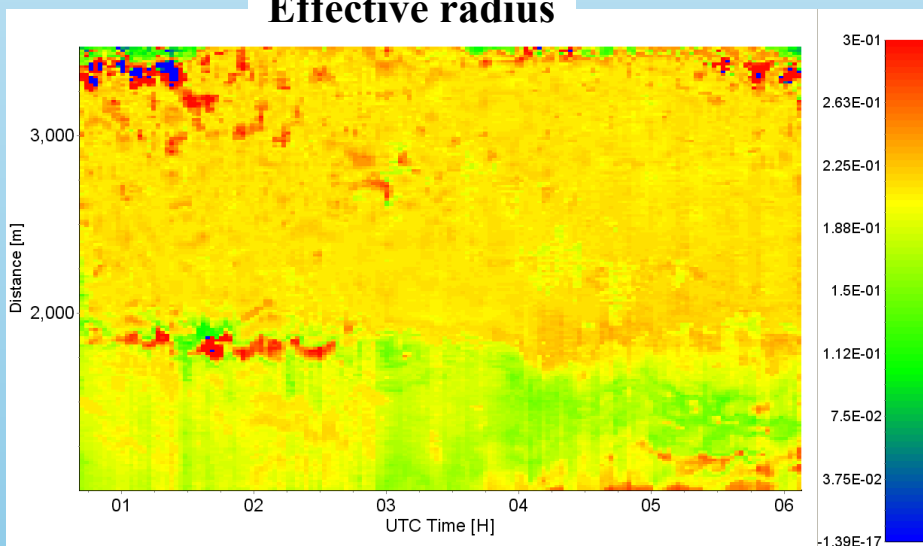
Extinction at 355 nm, km^{-1}



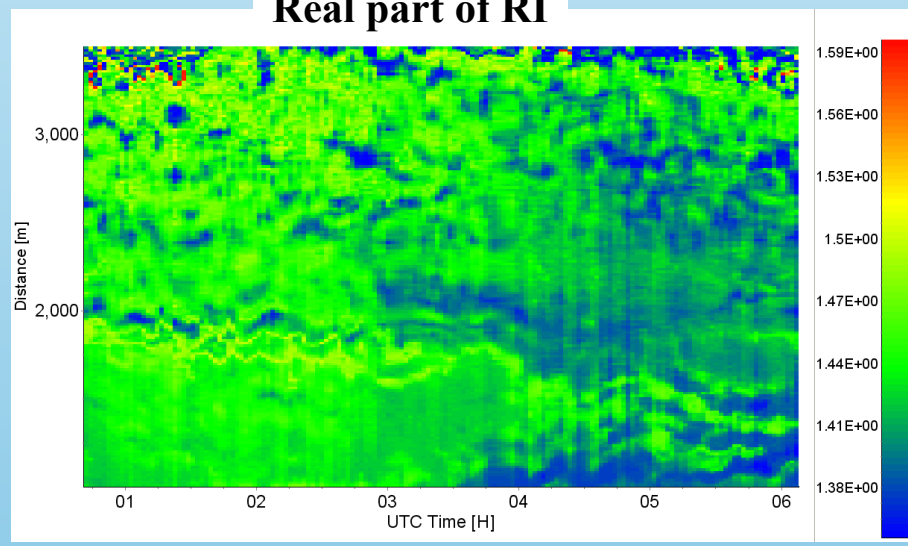
Volume, $\mu\text{m}^3/\text{cm}^3$



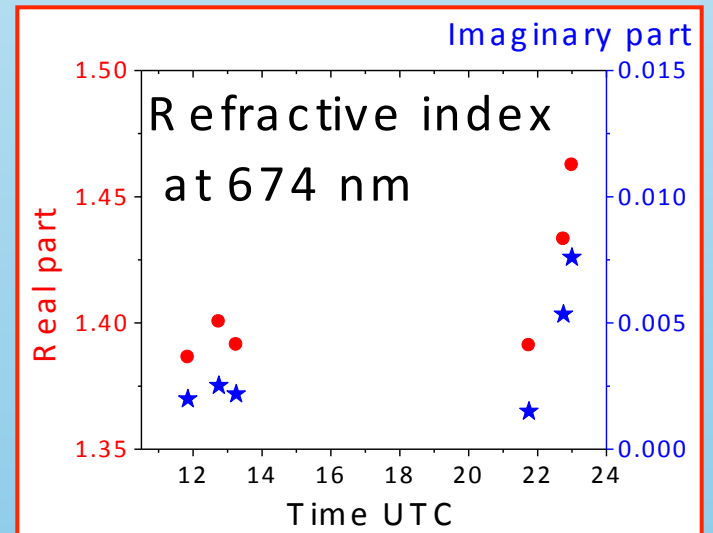
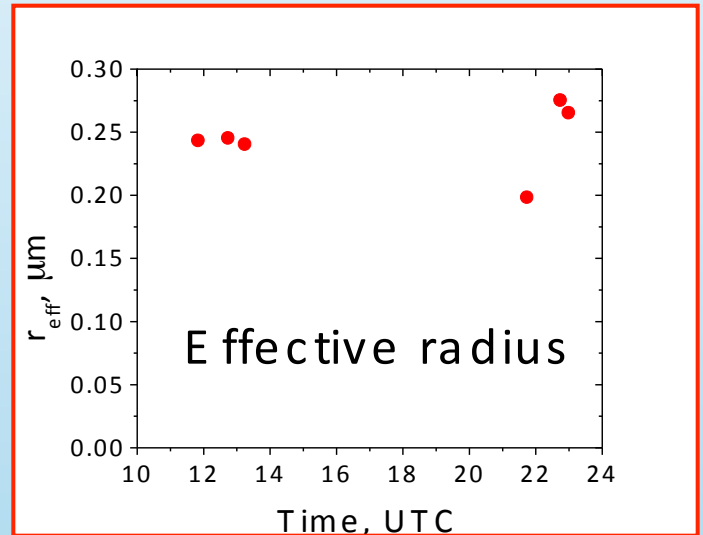
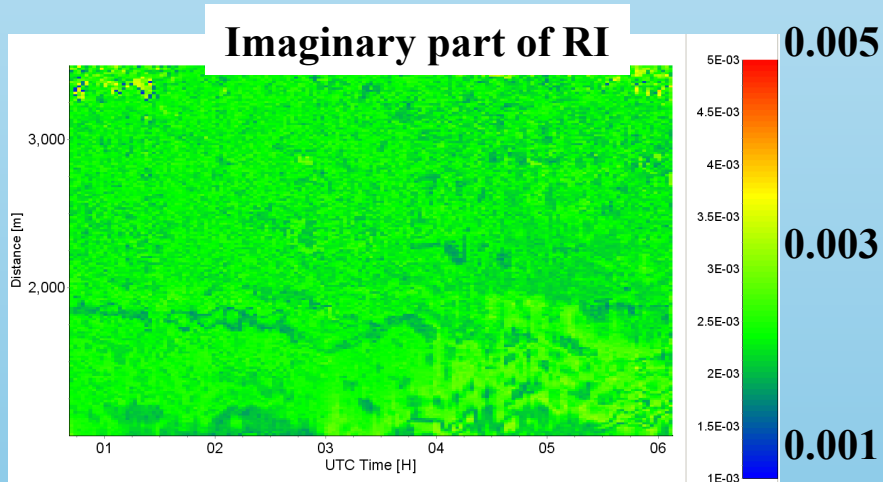
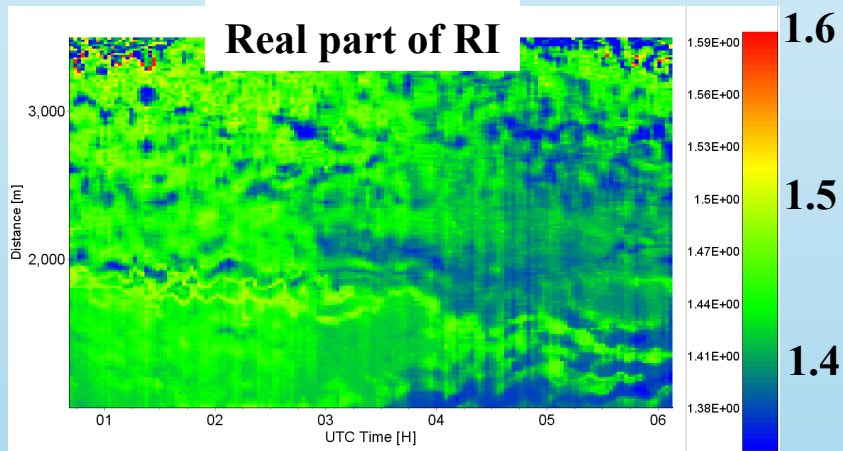
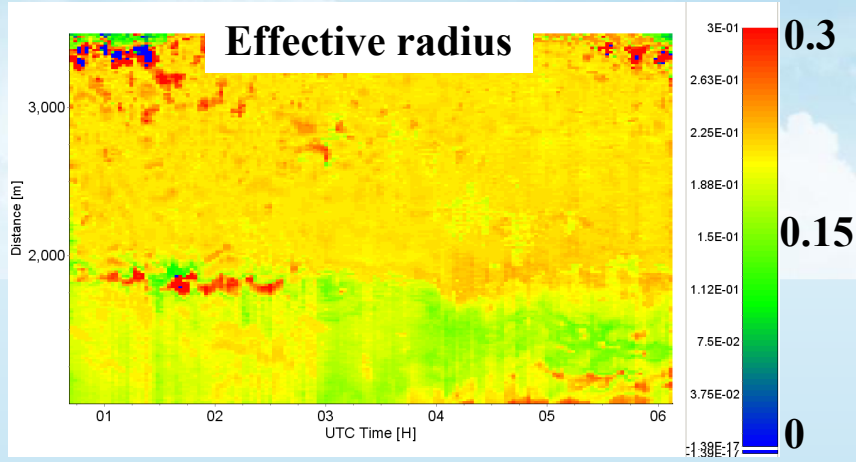
Effective radius



Real part of RI

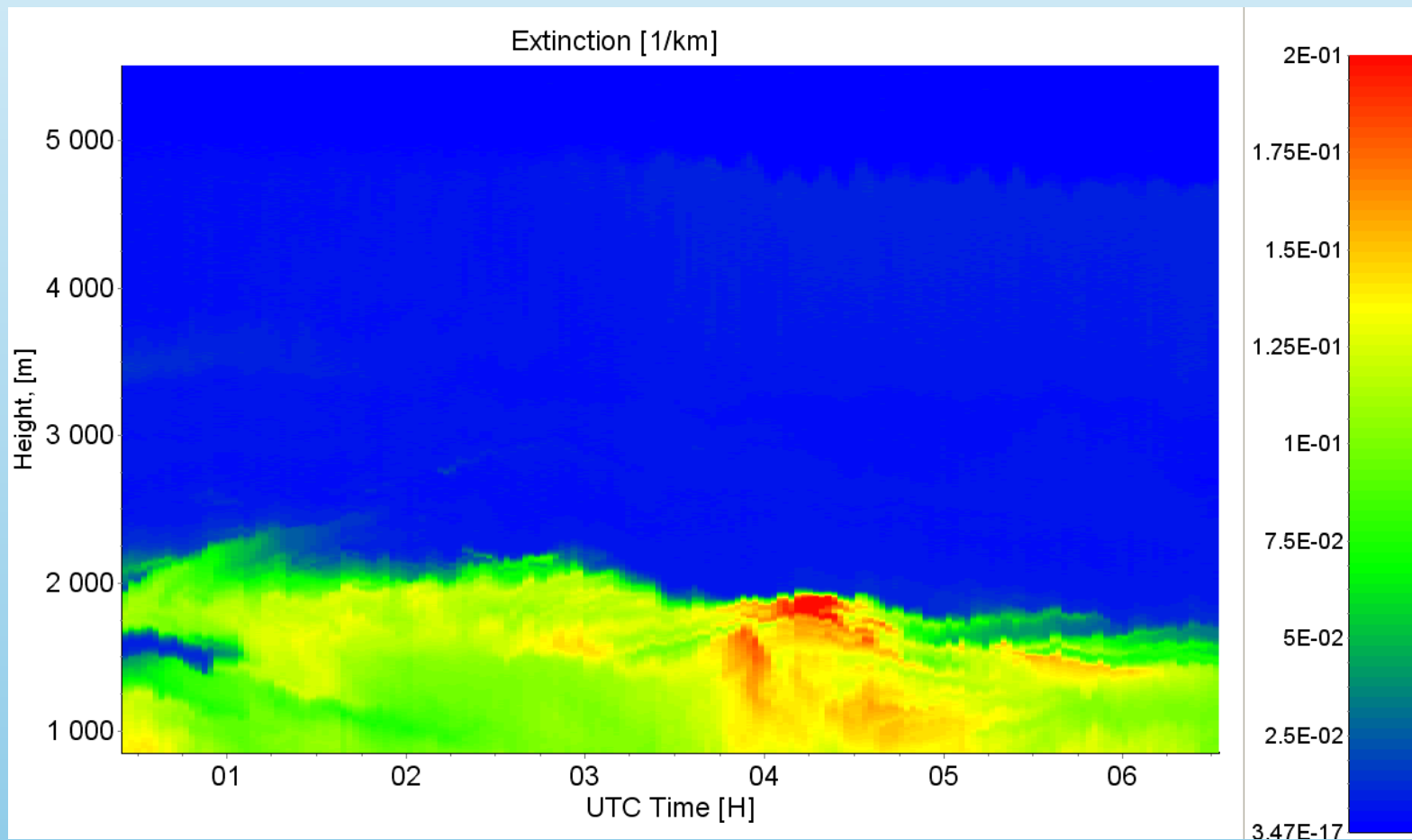


Comparison with AERONET



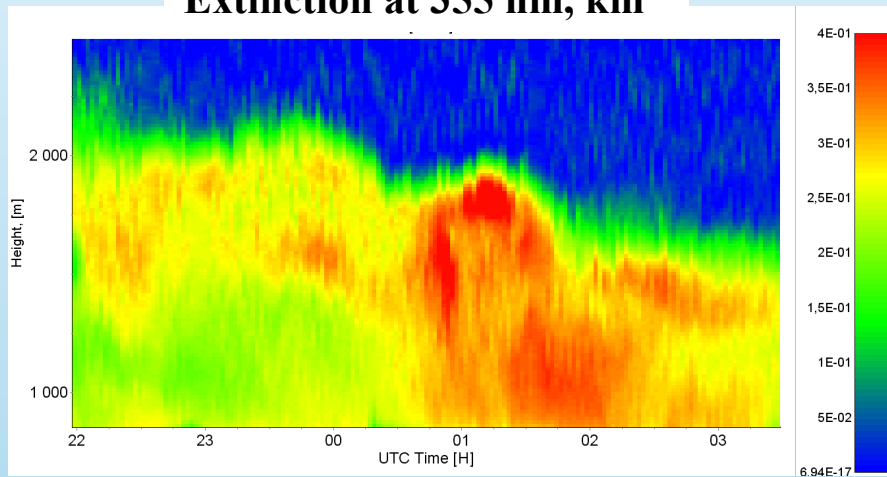
21 July 2011, GSFC

Extinction at 532 nm calculated by Klett.
Height res. – 7.5 m, temporal res. – 2 min.

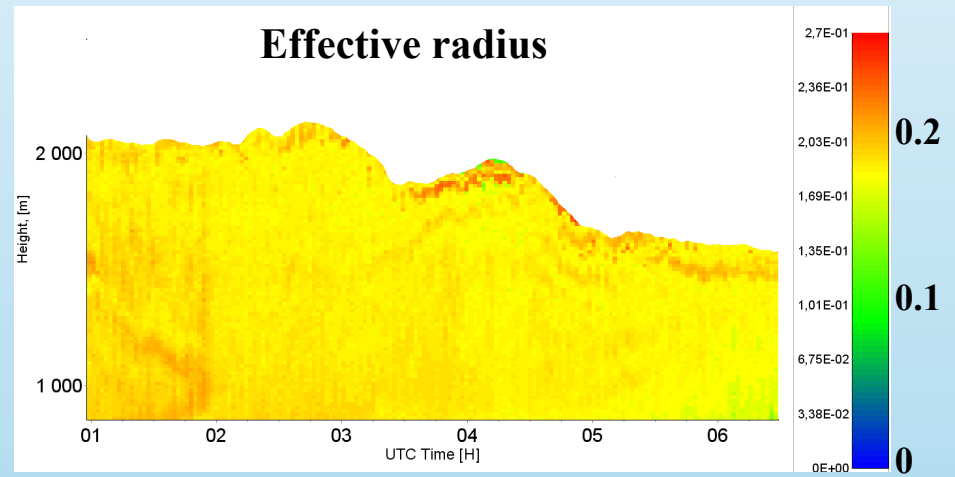


Retrievals for 21 July

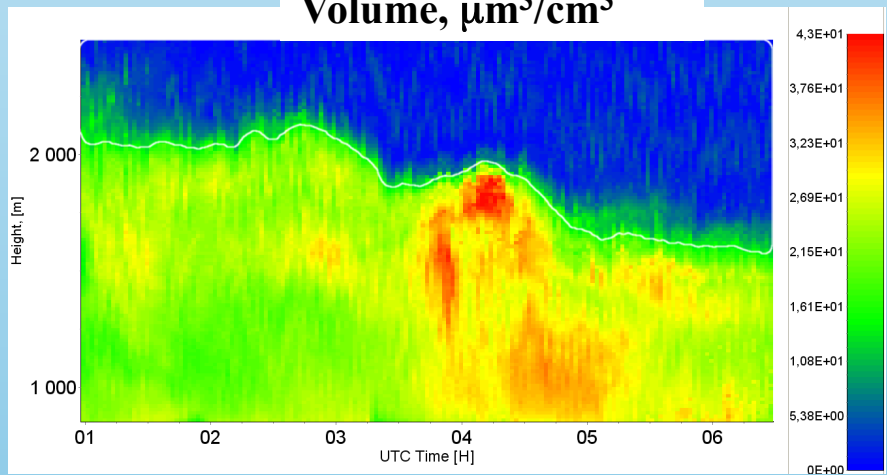
Extinction at 355 nm, km^{-1}



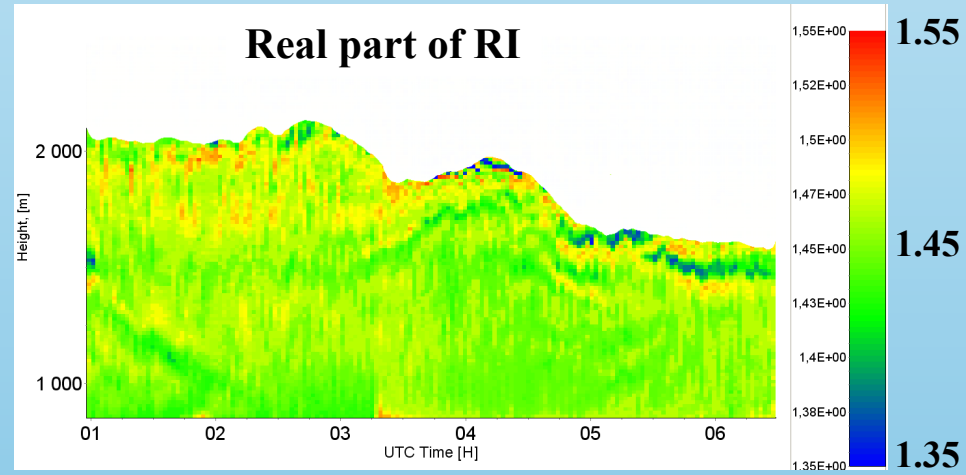
Effective radius



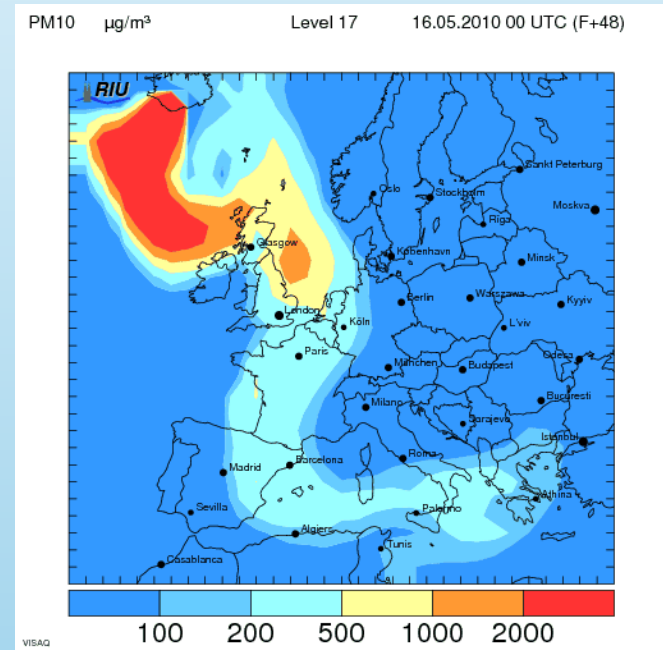
Volume, $\mu\text{m}^3/\text{cm}^3$



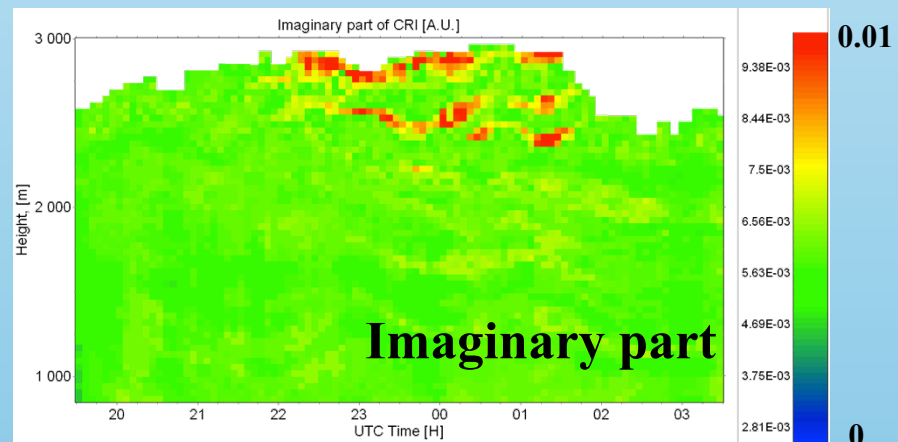
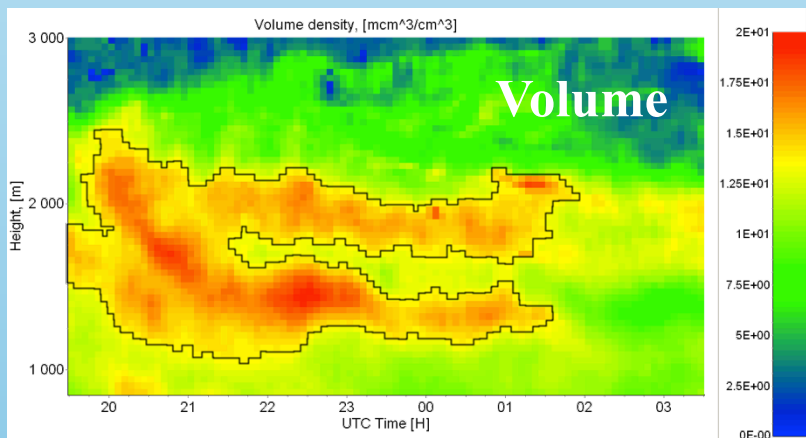
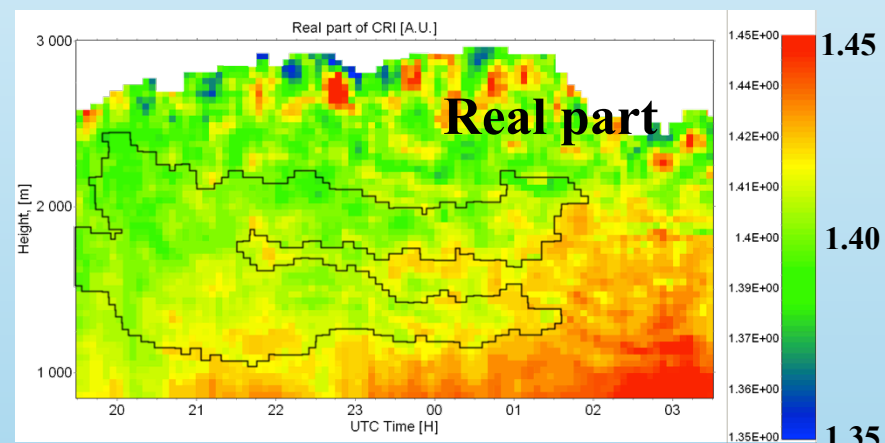
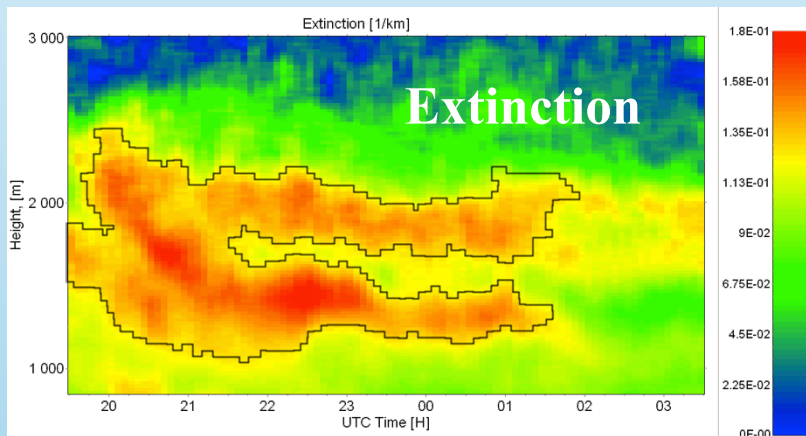
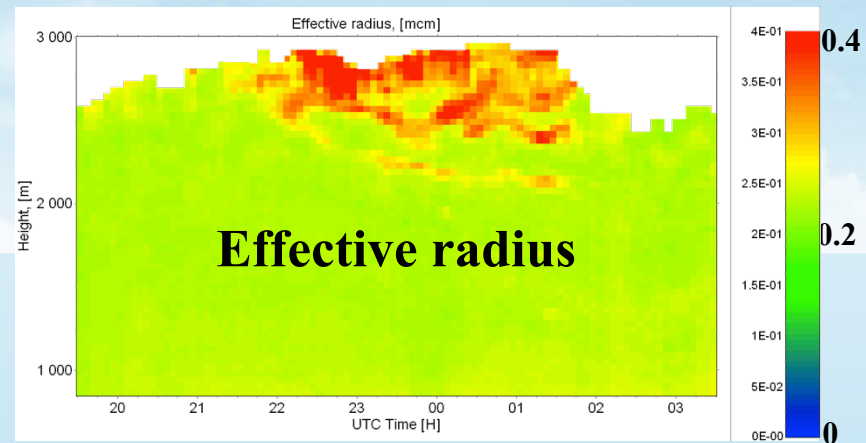
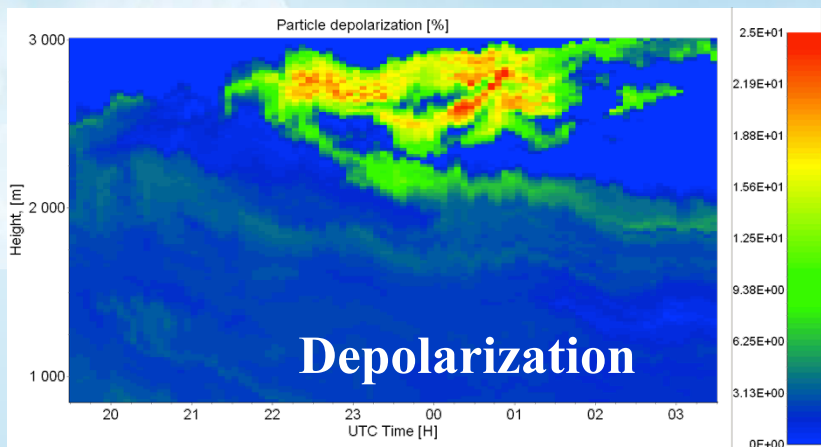
Real part of RI



Episode of volcanic ash intrusion on 20-21 May 2010, Istanbul



**Multiwavelength Raman lidar was installed in the
Spring 2009 in TÜBITAK (Turkey).**



Summary

- **Application of “kernels expansion” technique brings a significant increase in speed of computations. Time sequences of particle physical parameters can be obtained.**
- **Possibility to decrease number of input data is important for coming missions.**